

# Mobility Issues for LVSR

Randy Jones

(601) 634-4145

Greg Green

(601) 634-2871

12/17/99

20020503 075

<b>REPORT DOCUMENTATION PAGE</b>				<i>Form Approved</i> <b>OMB No. 0704-0188</b>	
Public reporting burden for this collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing this collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden to Department of Defense, Washington Headquarters Services, Directorate for Information Operations and Reports (0704-0188), 1215 Jefferson Davis Highway, Suite 1204, Arlington, VA 22202-4302. Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to any penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number. <b>PLEASE DO NOT RETURN YOUR FORM TO THE ABOVE ADDRESS.</b>					
<b>1. REPORT DATE (DD-MM-YYYY)</b> 17-12-1999		<b>2. REPORT TYPE</b> Mobility Issues Analysis		<b>3. DATES COVERED (From - To)</b>	
<b>4. Title AND SUBTITLE</b> NRMMII Stochastic Mobility Issues For Logistic Vehicle System  Replacement (LVSR)				<b>5a. CONTRACT NUMBER</b>	
				<b>5b. GRANT NUMBER</b>	
				<b>5c. PROGRAM ELEMENT NUMBER</b>	
				<b>5d. PROJECT NUMBER</b>	
<b>6. AUTHOR(S)</b> Greg Green, Randy Jones				<b>5e. TASK NUMBER</b>	
				<b>5f. WORK UNIT NUMBER</b>	
				<b>8. PERFORMING ORGANIZATION REPORT NUMBER</b>	
<b>7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES)</b>  Jacobs Sverdrup Technology Inc, 25 Clement Drive, Suite 101 Quantico, Virginia 22554				<b>10. SPONSOR/MONITOR'S ACRONYM(S)</b> MARCORSSYSCOM	
<b>9. SPONSORING / MONITORING AGENCY NAME(S) AND ADDRESS(ES)</b> Marine Corps Systems Command 2033 Barnett Ave Suite 315 Quantico, Virginia 22134-5010					
<b>12. DISTRIBUTION / AVAILABILITY STATEMENT</b> Distribution Statement A				<b>11. SPONSOR/MONITOR'S REPORT NUMBER(S)</b>	
<b>13. SUPPLEMENTARY NOTES</b> None					
<b>14. ABSTRACT</b> The purpose of this analysis was to identify vehicle parameters and terrain features that impede mobility, to forecast mobility over different mission areas of interest, and to identify vehicle parameter modifications that will improve LVSR mobility performance.					
<b>15. SUBJECT TERMS</b> NRMMII, HMMWV, LVS, AAV, M1A1, M1A2, PLS, and MTRV.					
<b>16. SECURITY CLASSIFICATION OF:</b> Unclassified			<b>17. LIMITATION OF ABSTRACT</b>  SAR	<b>18. NUMBER OF PAGES</b>  53	<b>19a. NAME OF RESPONSIBLE PERSON</b> Timothy L. McMahon
<b>a. REPORT</b>	<b>b. ABSTRACT</b> Unclassified	<b>c. THIS PAGE</b>			<b>19b. TELEPHONE NUMBER (include area code)</b> (540) 657-8000 ext#113

AQMO2-08-1416

## **Purpose**

- Implement Stochastic Mobility Modeling methodologies that assist in assessing/developing LVSR.

## **Scope**

- Use Stochastic Mobility Modeling to identify vehicle parameters and terrain features that impede mobility.
- Forecast mobility over different mission areas of interest.
- Identify vehicle parameter modifications which will improve LVSR mobility performance.

## NRMMII Summary

NRMMII - A computer-based collection of equations and algorithms designed to predict the steady-state operating capability of a given vehicle in a prescribed terrain.

### Areas

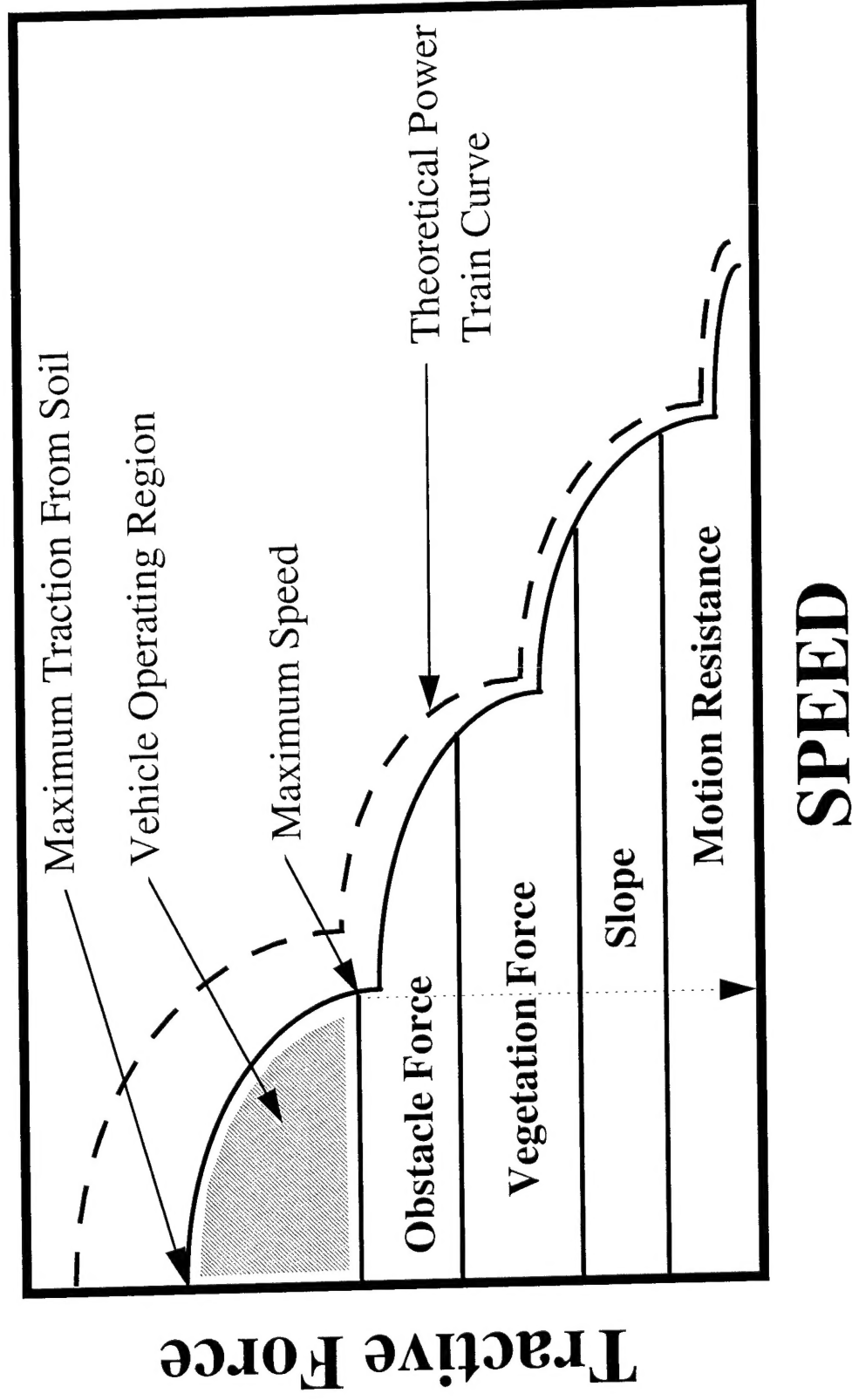
- Philippines (Mindanao Island)
- South Korea (Eastern Coast)
- Saudi Arabia/Kuwait (Eastern Coast)

### Scenarios

- Dry Normal
  - Average soil strength and moisture for the 30 driest days in an average rainfall year
- Wet Slippery
  - Average soil strength and moisture for the 30 wettest days in an average rainfall year

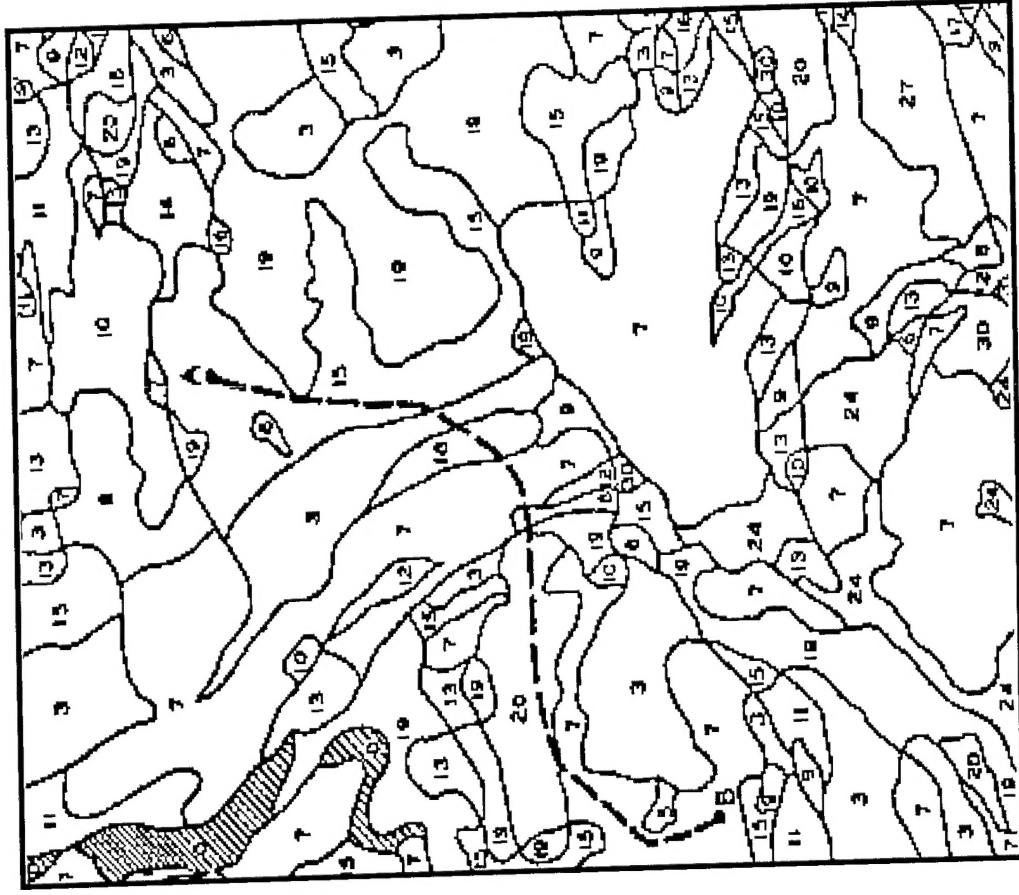
*Waterways Experiment Station*

# Tractive Force Speed Curve



Waterways Experiment Station

## Terrain Unit Mapping



*Waterways Experiment Station*

## Terrain Parameters

- Surface Roughness
- Soil Depth to Bedrock
- Road Super-elevation
- Angle
- Slope Percent
- Obstacle Approach Angle
- Obstacle Height
- Obstacle Length
- Obstacle Spacing
- Obstacle Width
- Soil Strength
- Recognition Distance
- Road Radius of Curvature
- Stem Spacing
- Stem Diameter
- Standing Water Depth

*Waterways Experiment Station*

# Significant Vehicle Parameters

## Vehicle Geometry

ACD Aerodynamic drag coefficient.  
 EYEHGT Driver's eye-height above ground.  
 PBF Maximum pushbar force vehicle can withstand overriding vegetation.  
 PBHT Height of pushbar above ground.  
 PFA Vehicle projected frontal area.  
 TL Vehicle length from 1st wheel to last wheel.  
 VULEN Length of each vehicle unit.  
 WDTH Maximum combination vehicle width.

## Power Train

CID Engine displacement.  
 FD Final drive gear ratio and efficiency.  
 QMAX Maximum net torque from each engine.  
 REVMT Tire revolutions per mile for each assembly.  
 TCASE Engine to torque-converter gear ratio and efficiency.  
 TRANS Transmission gear ratios and efficiencies.  
 XBRCOF Combination vehicle braking coefficient.

## Traction Components

DFLCT Tire Deflection for each assembly and deflection case.  
 DIAW Undelected tire diameter for each assembly.  
 SECTW Tire nominal section width.  
 VTIRMX Maximum tire speed limit for each deflection scenario.

## Suspension

VRIDE Limited speeds for RMS roughness versus limited speed data.  
 VOOB Limiting speeds for obstacle height versus 2.5 G limited speed data.

## Weight

WGHT Weight beneath each vehicle assembly.

Waterways Experiment Station

## **NRMMII "NOGO" Reason Codes**

- Visibility
- Soil and Slope Resistance
- Obstacle Clearance Interference
- Obstacle Belly Interference
- Vegetation Override
- Obstacle Override
- Soil NO-GO
- Sliding
- Tipping

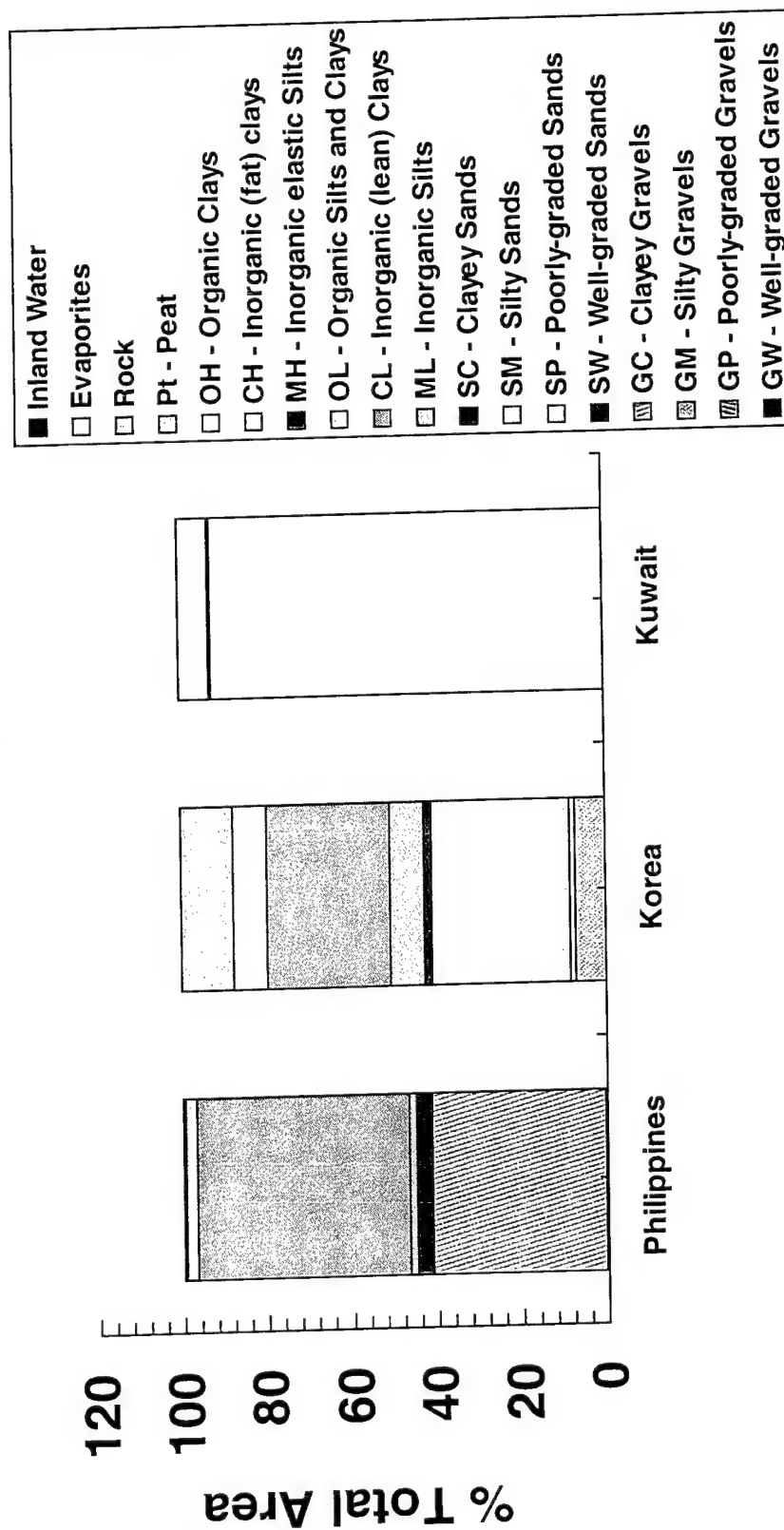
*Waterways Experiment Station*

## **NRMMII "GO" Reason Codes**

- Ride Dynamics Limit
- Tire Speed Limit
- Soil, Slope, & Veg Resistance
- Visibility
- Maneuver Around Obst and Veg
- Maneuver Around Veg
- Obstacle Impact Speed
- Obstacle Override Force
- Driver Prudence Over Veg
- Sliding on Curves
- Tipping on Curves

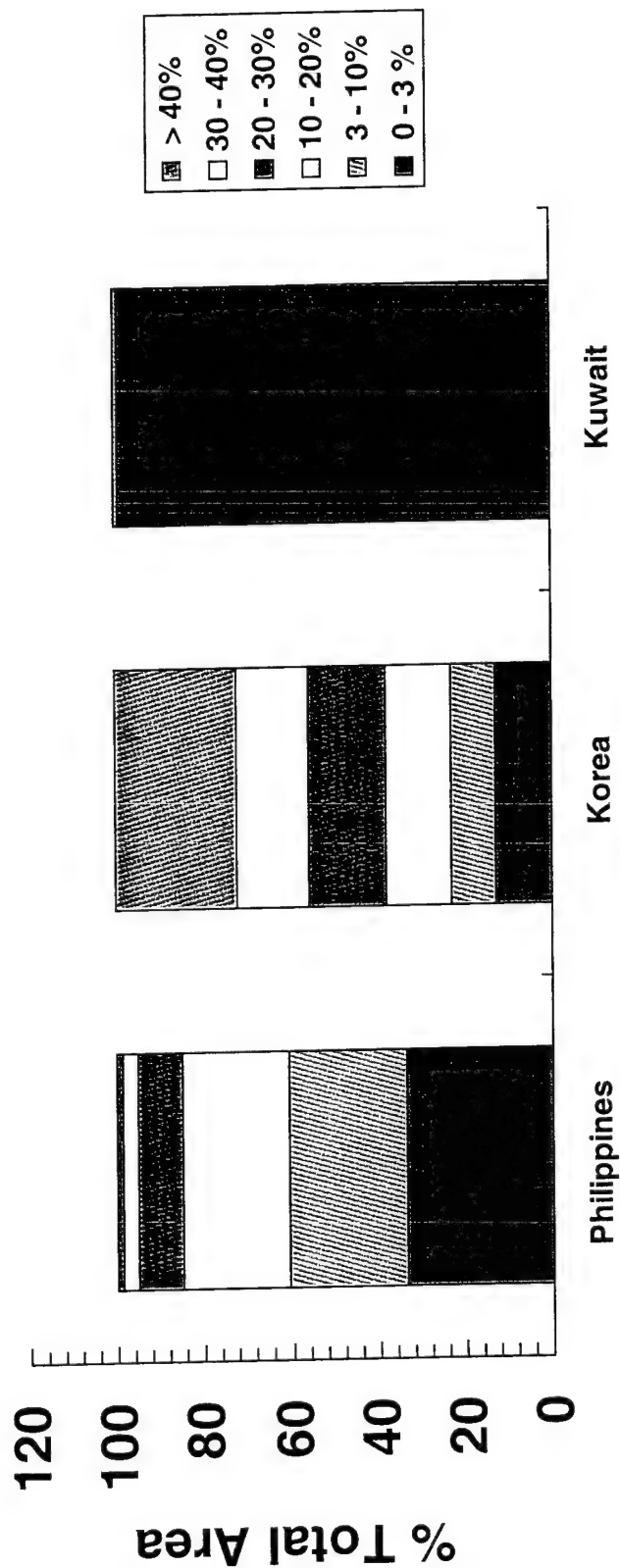
*Waterways Experiment Station*

# Soil Type Distributions for the Three Study Area



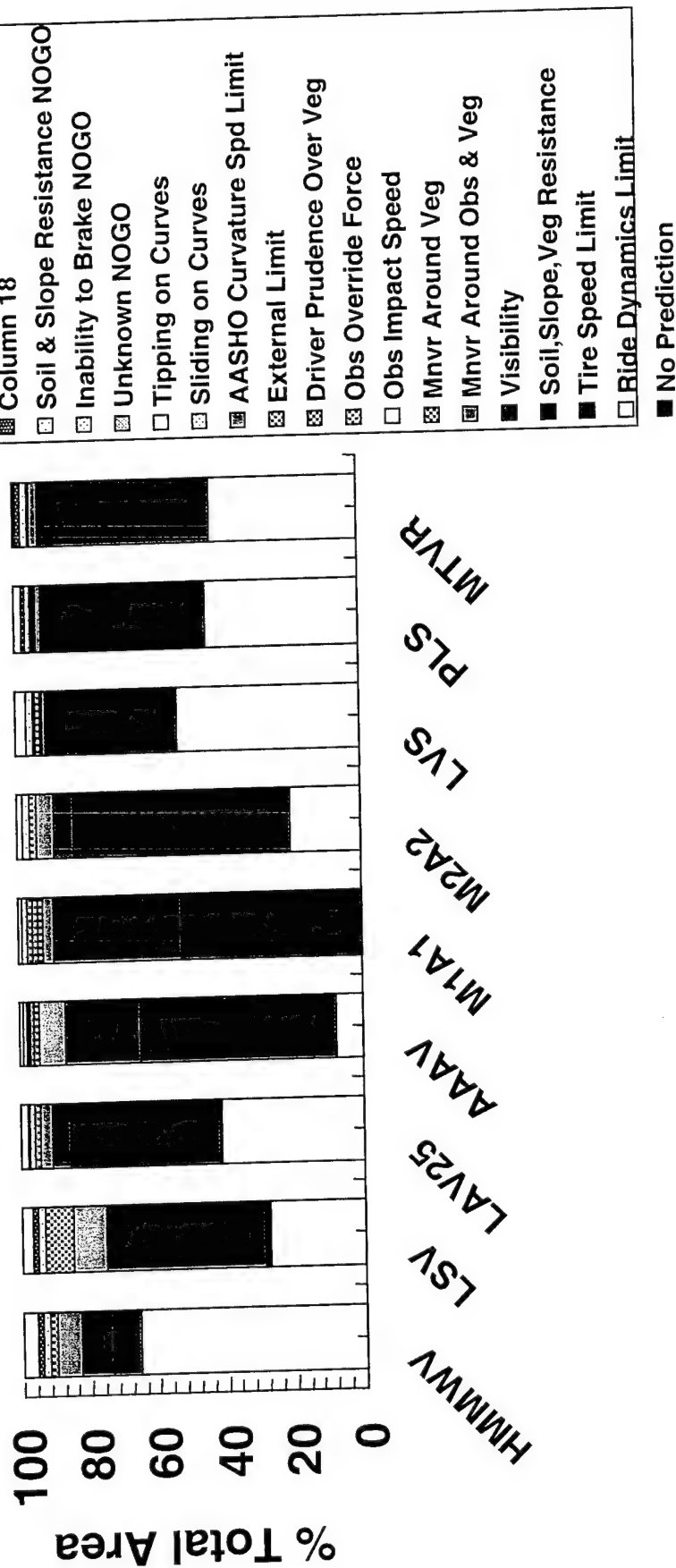
Waterways Experiment Station

# Slope Distributions for the Three Study Areas



Waterways Experiment Station

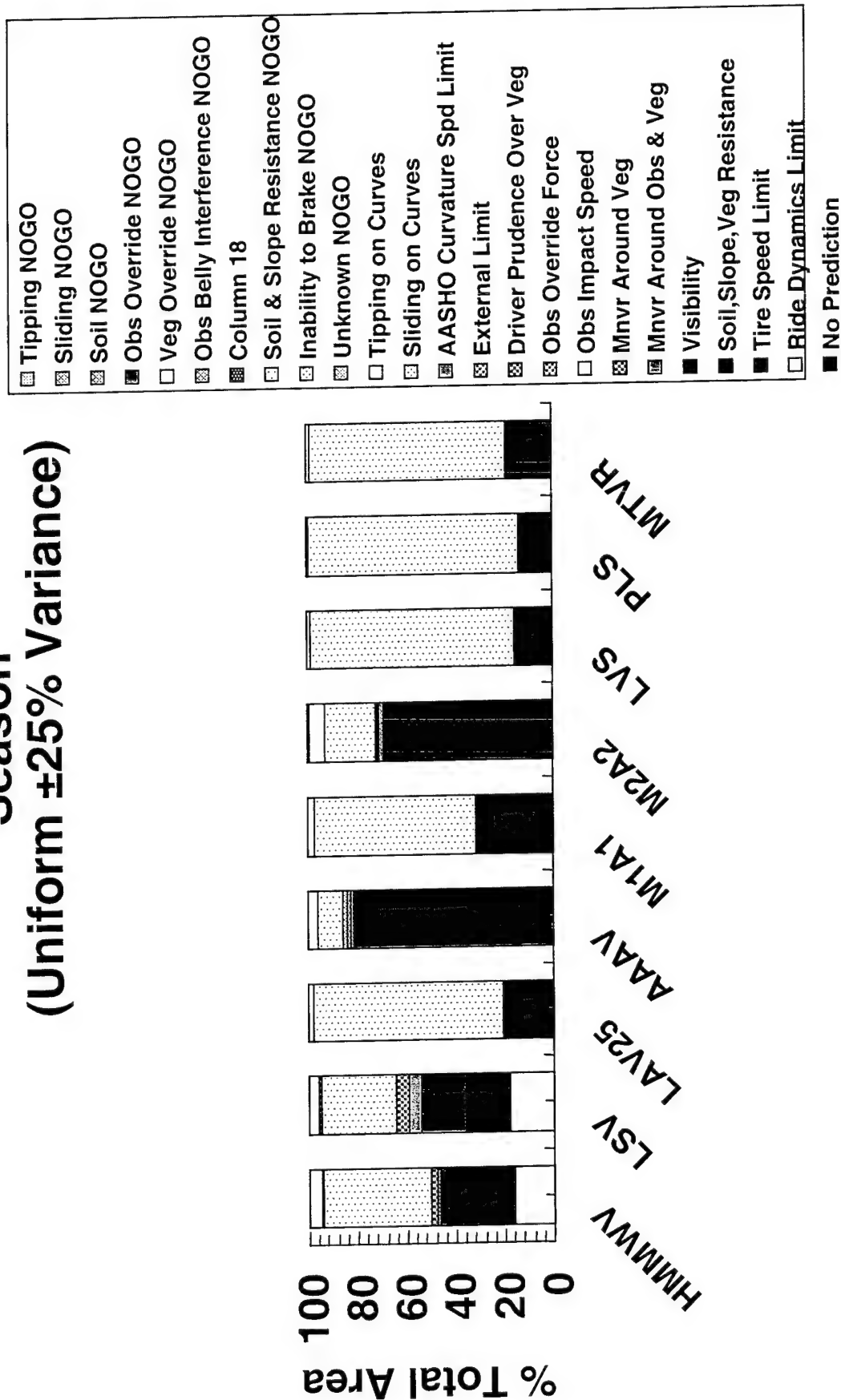
# Philippines for Off-Road and Dry-Normal Season (Uniform $\pm 25\%$ Variance)



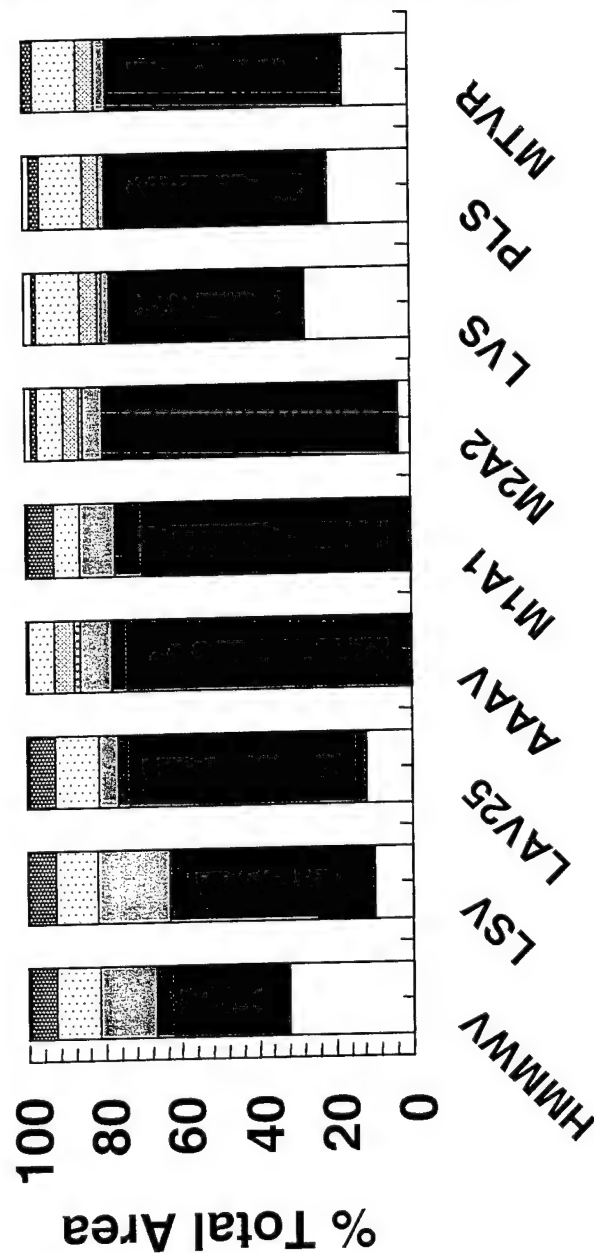
Waterways Experiment Station

# Philippines for Off-Road and Wet-Slippery Season (Uniform $\pm 25\%$ Variance)

Waterways Experiment Station



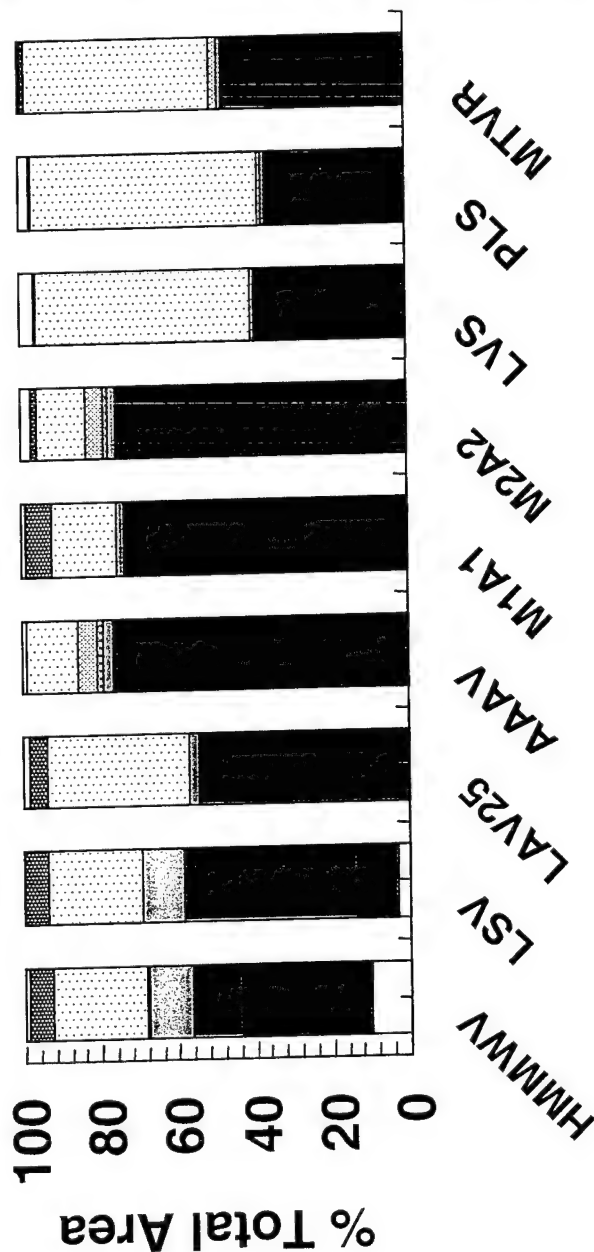
# Korea for Off-Road and Dry-Normal Season (Uniform $\pm 25\%$ Variance)



Waterways Experiment Station

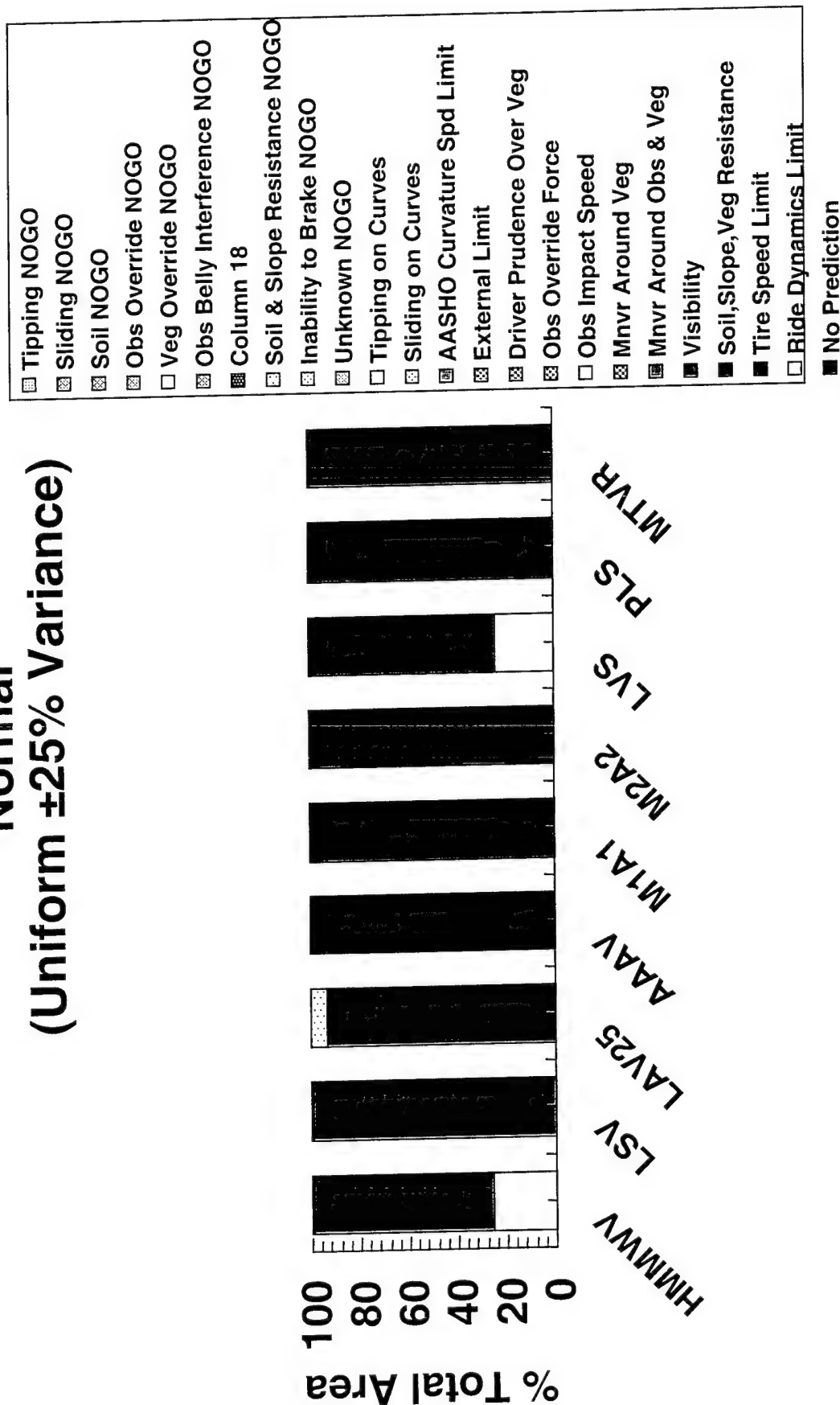
# Korea for Off-Road and Wet-Slippery Season (Uniform $\pm 25\%$ Variance)

Waterways Experiment Station



# Saudi Arabia/Kuwait for Off-Road and Dry- Normal (Uniform $\pm 25\%$ Variance)

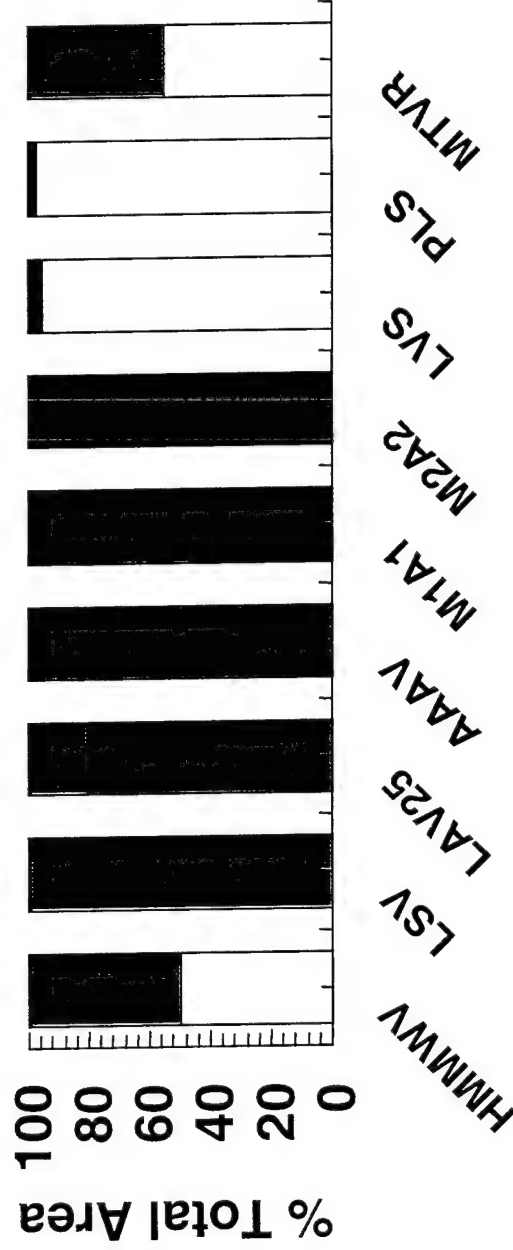
Waterways Experiment Station



# Saudi Arabia/Kuwait for Off-Road and Wet-Slipper

(Uniform  $\pm 25\%$  Variance)

Waterways Experiment Station

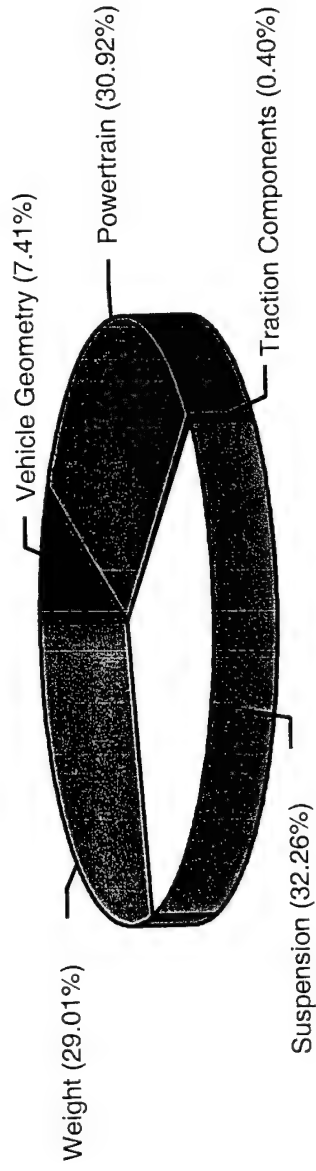


- Tipping NOGO
- Sliding NOGO
- Soil NOGO
- Obs Override NOGO
- Veg Override NOGO
- Obs Belly Interference NOGO
- Column 18
- Soil & Slope Resistance NOGO
- Inability to Brake NOGO
- Unknown NOGO
- Tipping on Curves
- Sliding on Curves
- AASHO Curvature Spd Limit
- External Limit
- Driver Prudence Over Veg
- Obs Override Force
- Obs Impact Speed
- Mnvr Around Veg
- Mnvr Around Obs & Veg
- Visibility
- Soil, Slope, Veg Resistance
- Tire Speed Limit
- Ride Dynamics Limit
- No Prediction

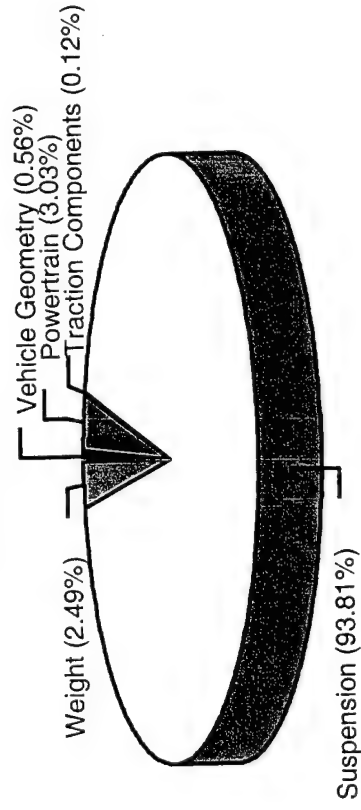
# Significant LVS Vehicle Parameters

## Philippines, Off-Road, 20% Variance

DRY NORMAL

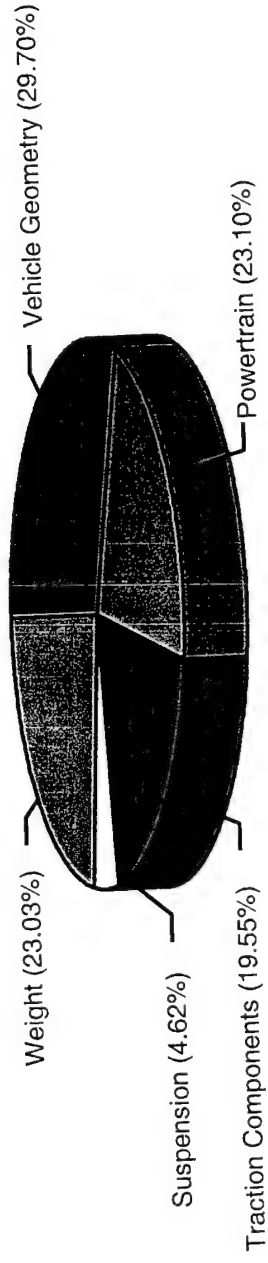


WET SLIPPERY

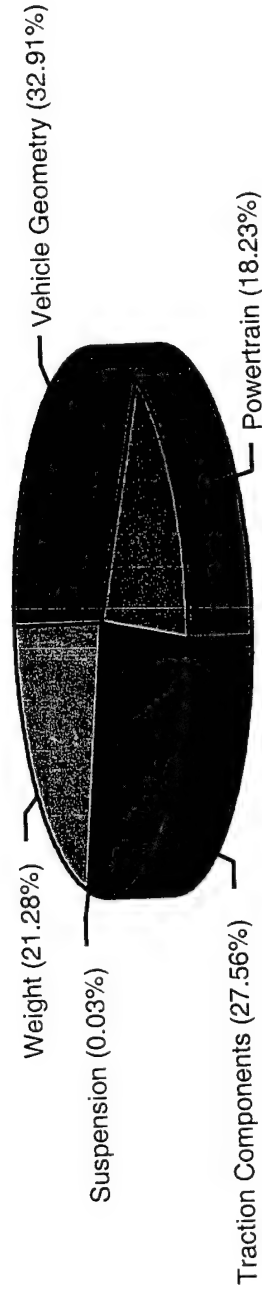


# Significant LVS Vehicle Parameters South Korea, Off-Road, 20% Variance

DRY NORMAL



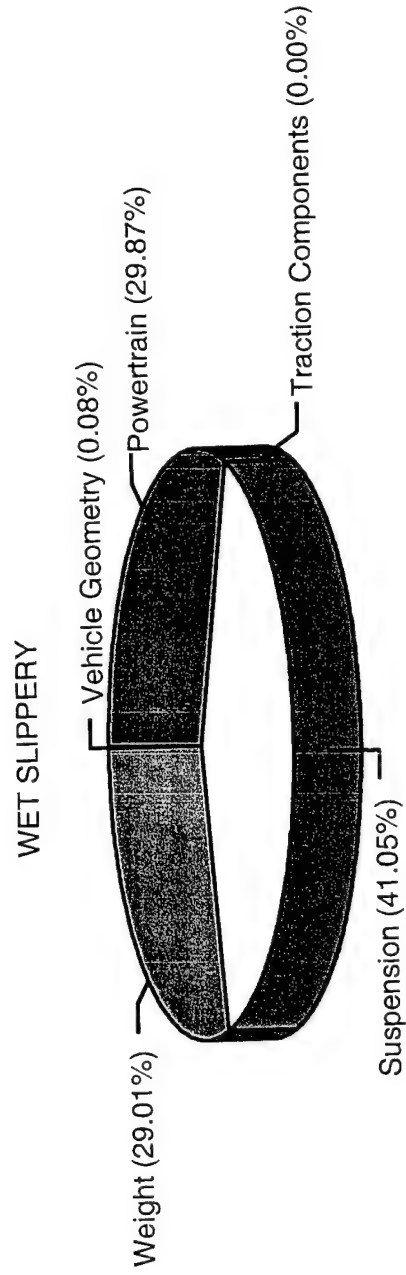
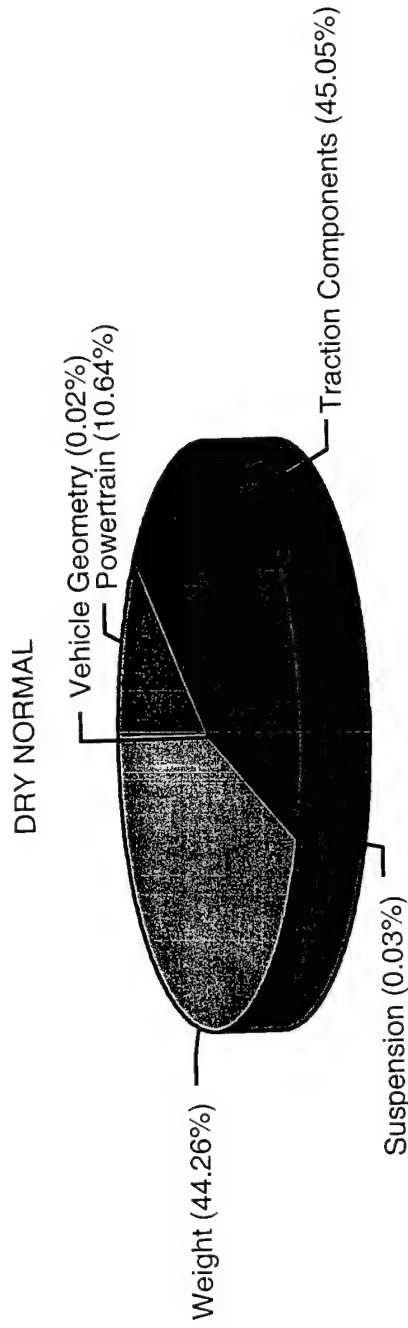
WET SLIPPERY



Waterways Experiment Station

# Significant LVS Vehicle Parameters

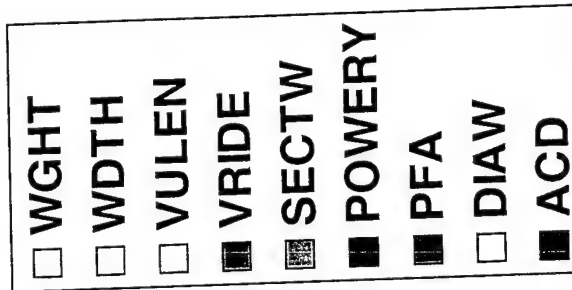
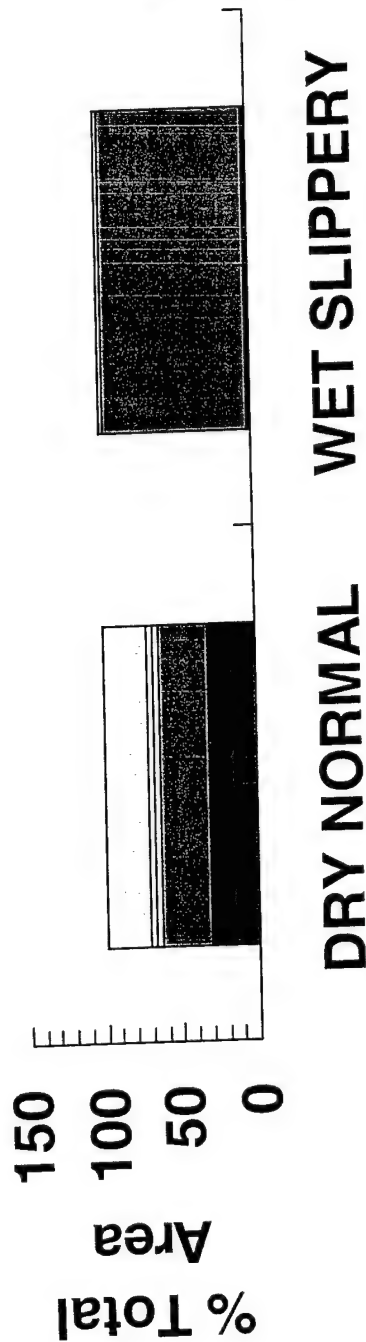
## Kuwait, Off-Road, 20% Variance



Waterways Experiment Station

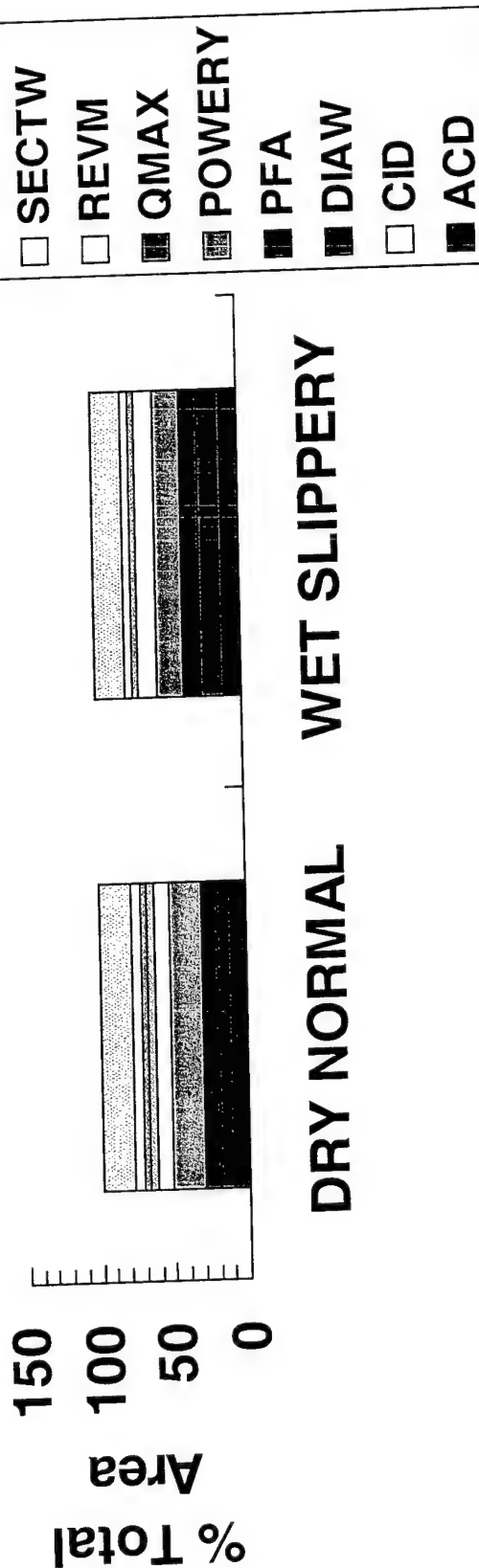
# Significant LVS Vehicle Parameters Mindanao, Philippines, Off- Road, 20% Variance

Waterways Experiment Station



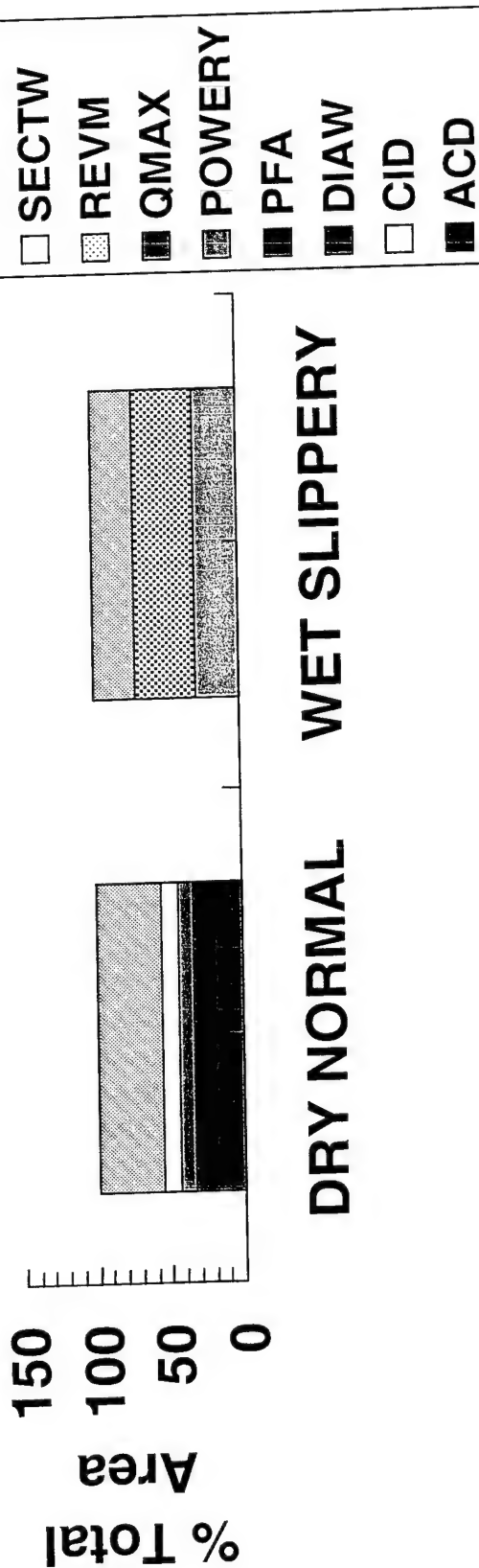
# Significant LVS Vehicle Parameters 3421i, South Korea, Off- Road, 20% Variance

Waterways Experiment Station



# Significant LVS Vehicle Parameters 5546i, Saudi Arabia/Kuwait, Off-Road, 20% Variance

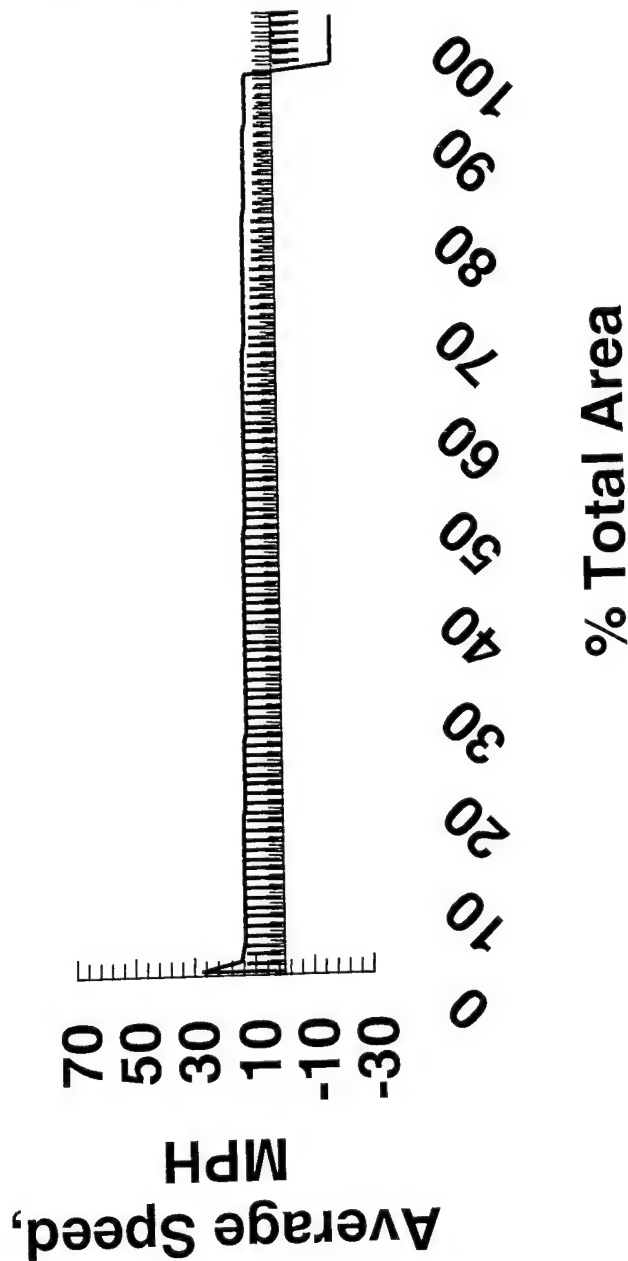
Waterways Experiment Station



# LVS Speed/Reason Profile Mindanao, Philippines, Off-Road, 100 Iterations

Dry Normal 50th Percentile Speed ( $\pm 25\%$ )

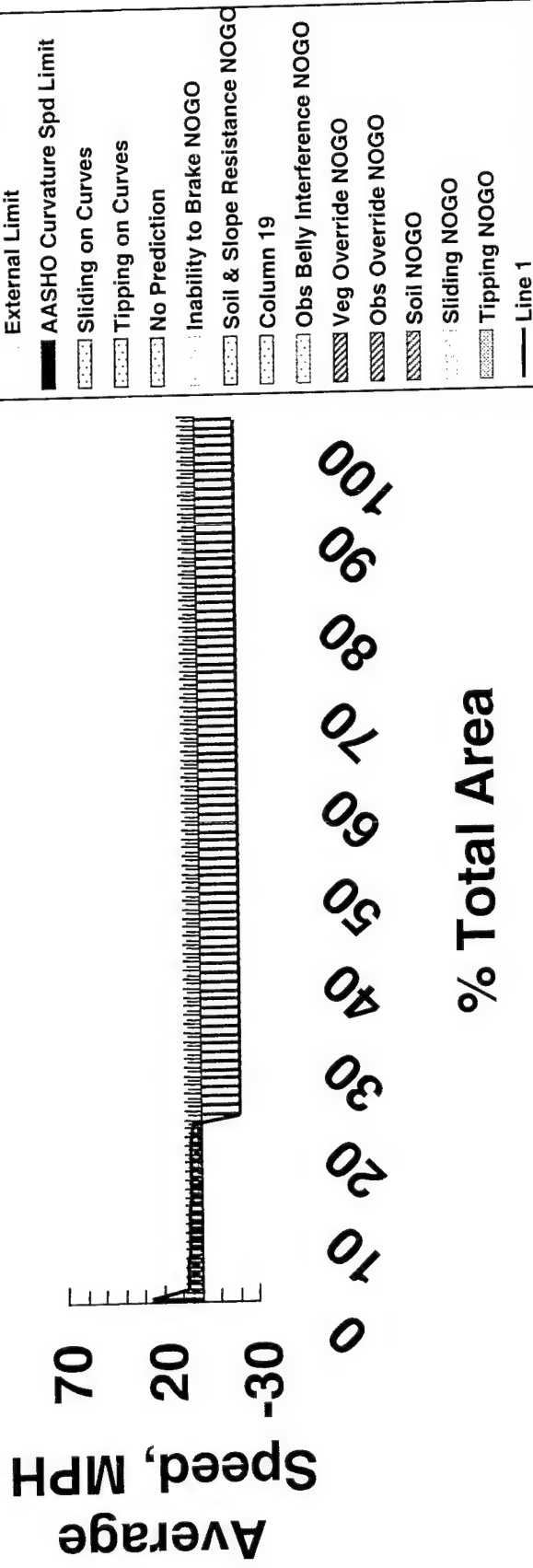
Waterways Experiment Station



No Prediction	Soil & Slope Resistance NOGO
Ride Dynamics Limit	Column 19
Tire Speed Limit	Obs Belly Interference NOGO
Soil, Slope, Veg Resistance	Veg Override NOGO
Visibility	Obs Override NOGO
Mnvr Around Obs & Veg	Soil NOGO
Mnvr Around Veg	Sliding NOGO
Obs Impact Speed	Tipping NOGO
Obs Override Force	Line 1
Driver Prudence Over Veg	
External Limit	
AASHO Curvature Spd Limit	
Sliding on Curves	
Tipping on Curves	
No Prediction	
Inability to Brake NOGO	

# LVS Speed/Reason Profile Mindanao, Philippines, Off-Road, 100 Iterations Wet Slippery 50th Percentile Speed ( $\pm 25\%$ )

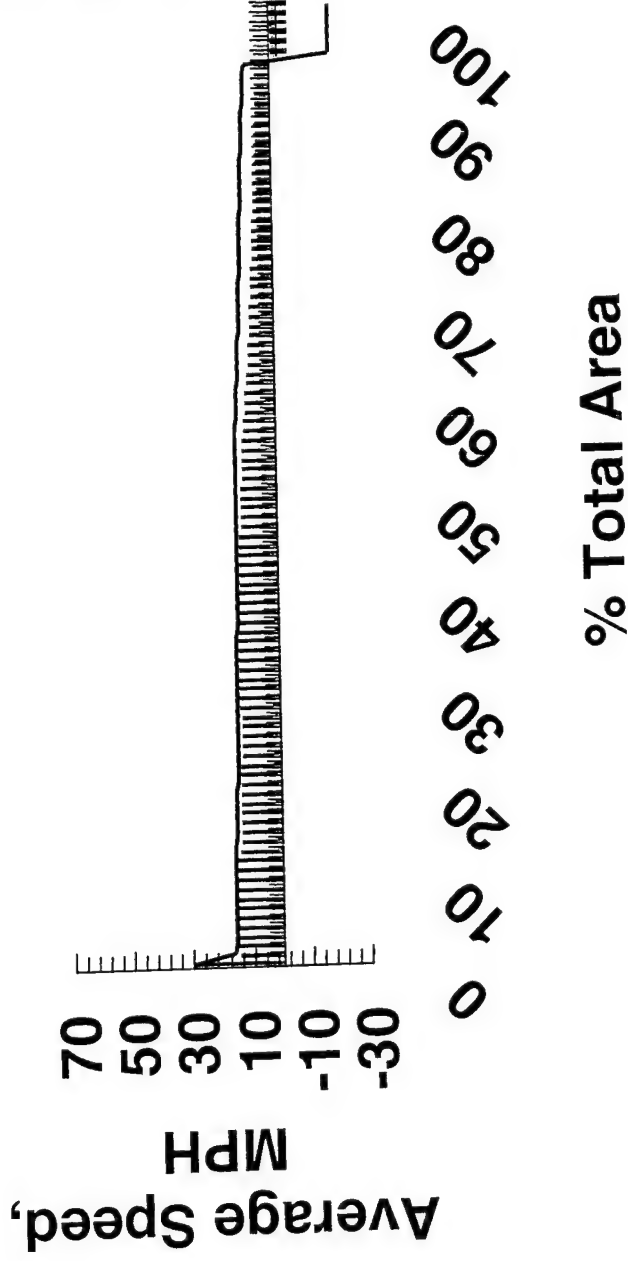
Waterways Experiment Station



# PLS Speed/Reason Profile Mindanao, Philippines, Off-Road, 100 Iterations

Dry Normal 50th Percentile Speed ( $\pm 25\%$ )

Waterways Experiment Station

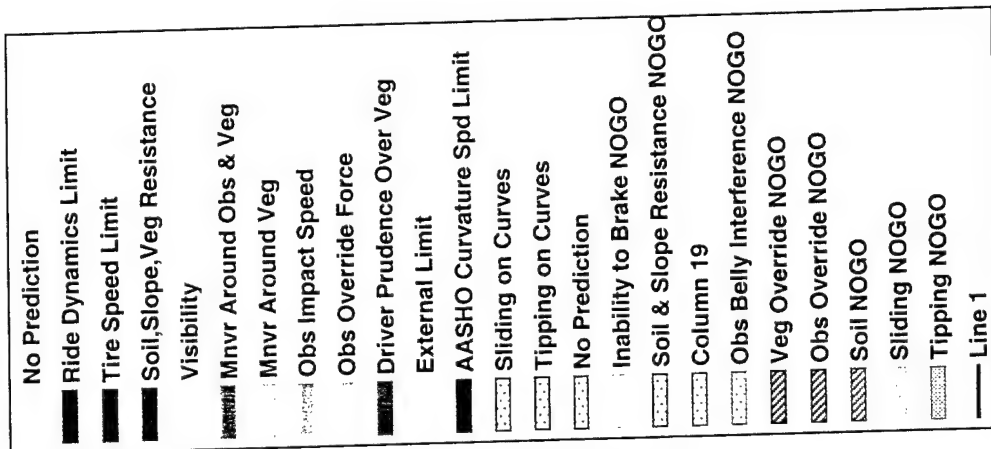
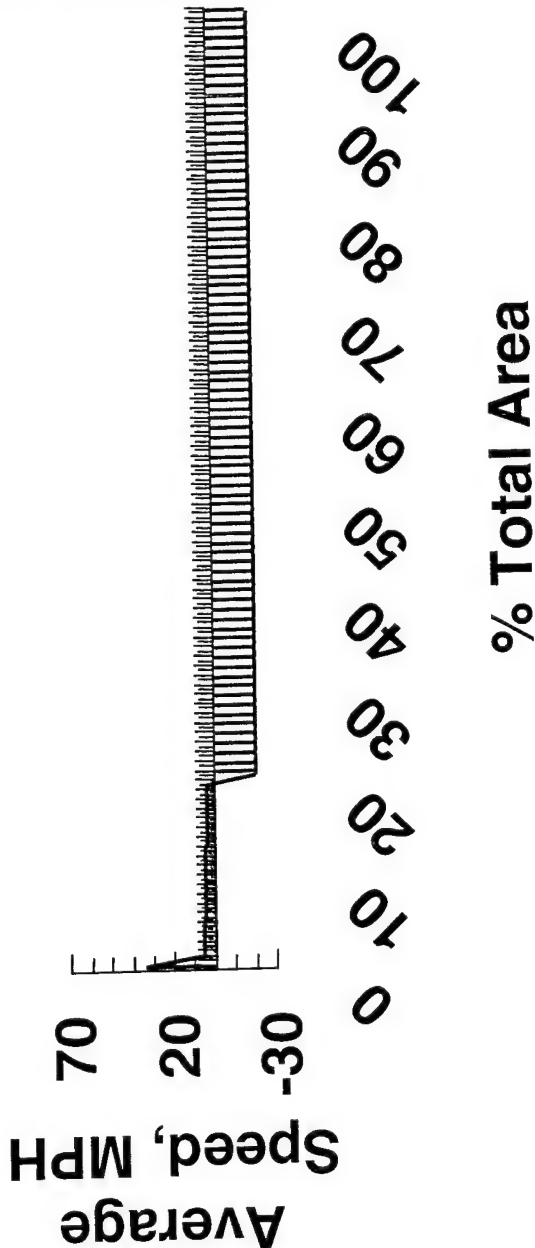


# PLS Speed/Reason Profile Mindanao, Philippines, Off-Road, 100

Iterations

Wet Slippery 50th Percentile Speed  
(±25%)

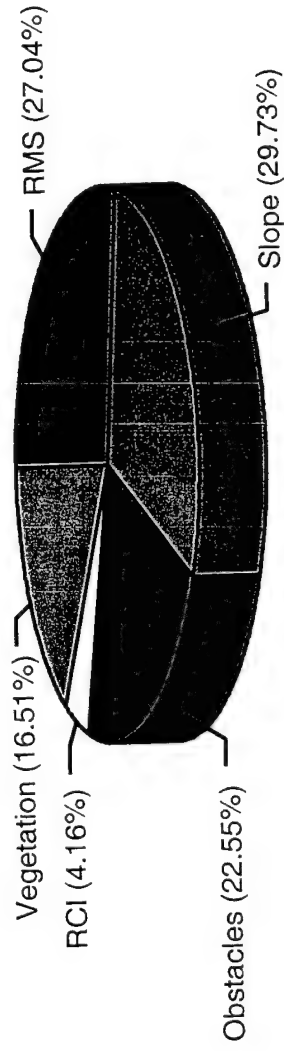
Waterways Experiment Station



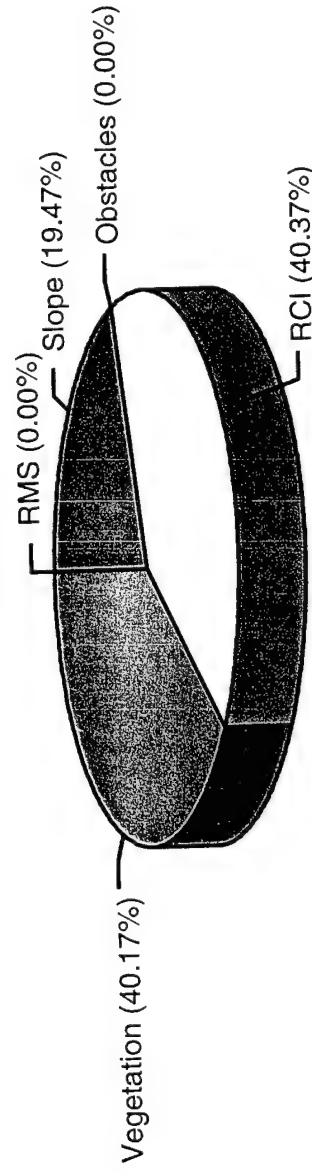
# Significant Terrain Parameters for LVS

## Philippines, Off-Road, 25% Variance

DRY NORMAL



WET SLIPPERY

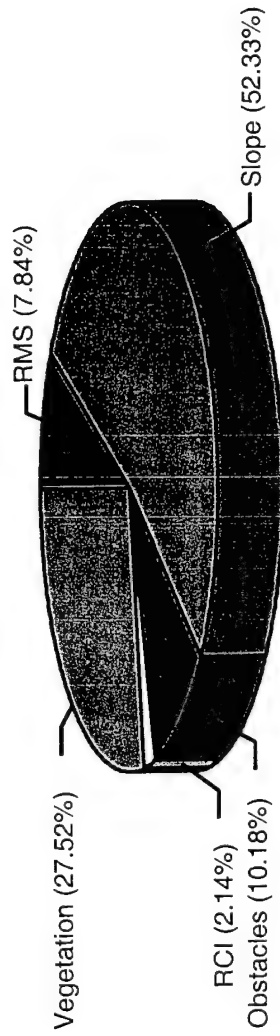


Waterways Experiment Station

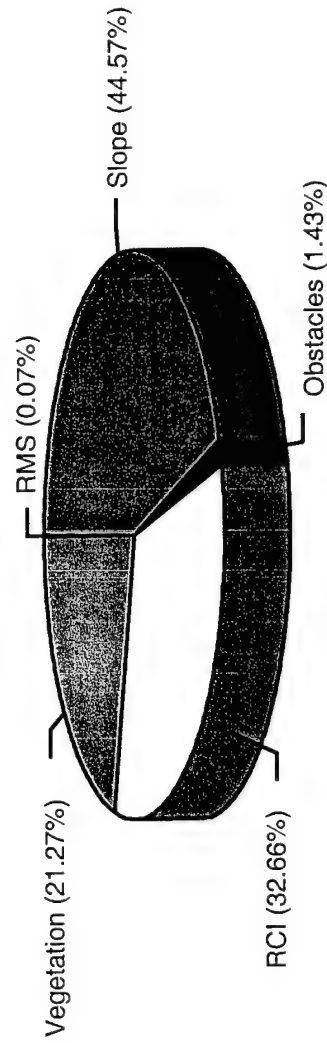
# Significant Terrain Parameters for LVS

## Korea, Off-Road, 25% Variance

DRY NORMAL



WET SLIPPERY

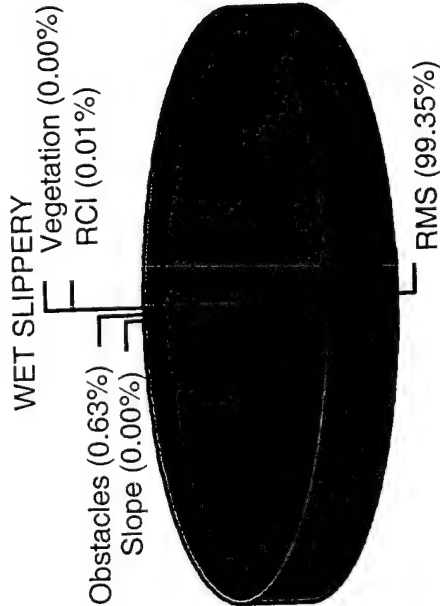
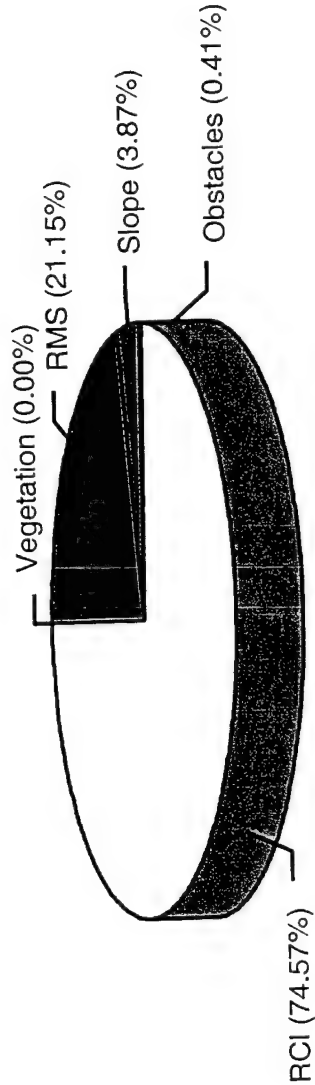


Waterways Experiment Station

# Significant Terrain Parameters for LVS

## Kuwait, Off-Road, 25% Variance

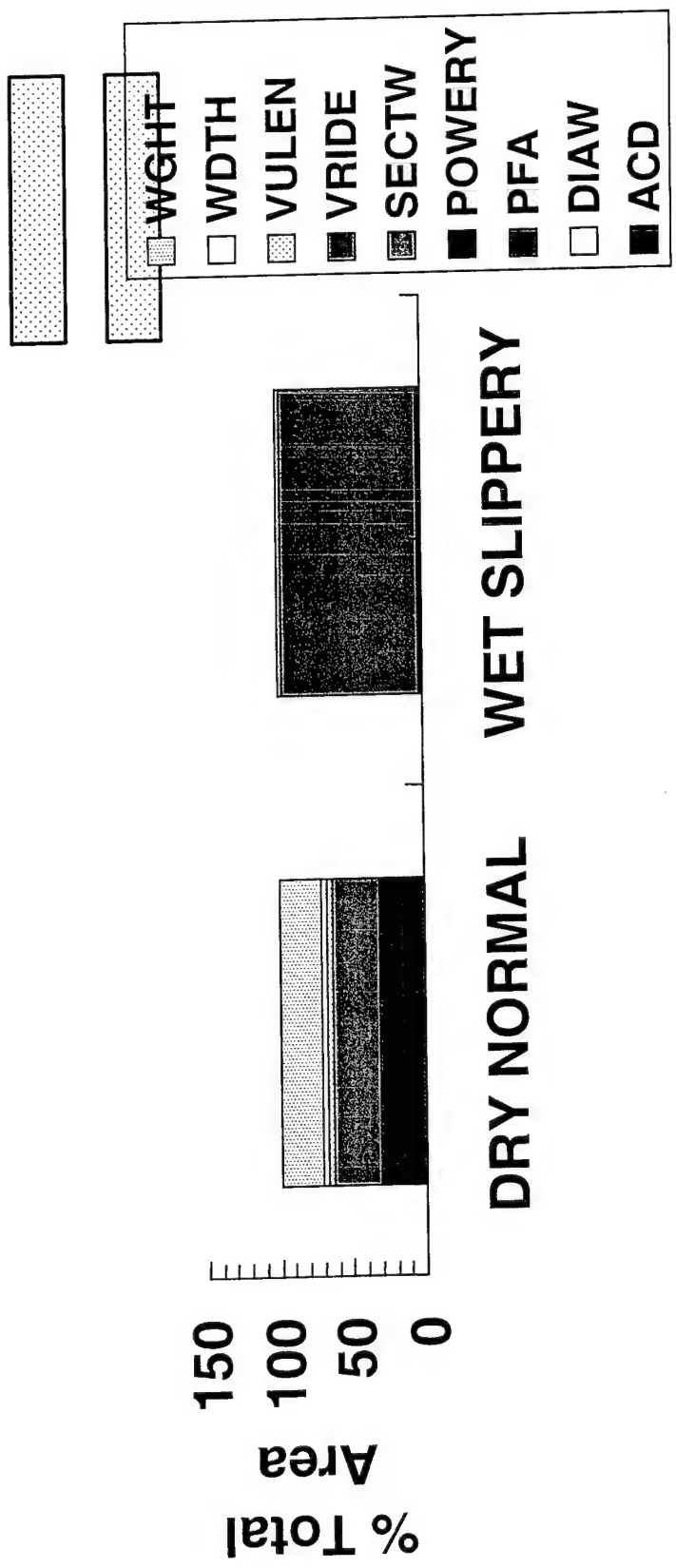
DRY NORMAL



Waterways Experiment Station

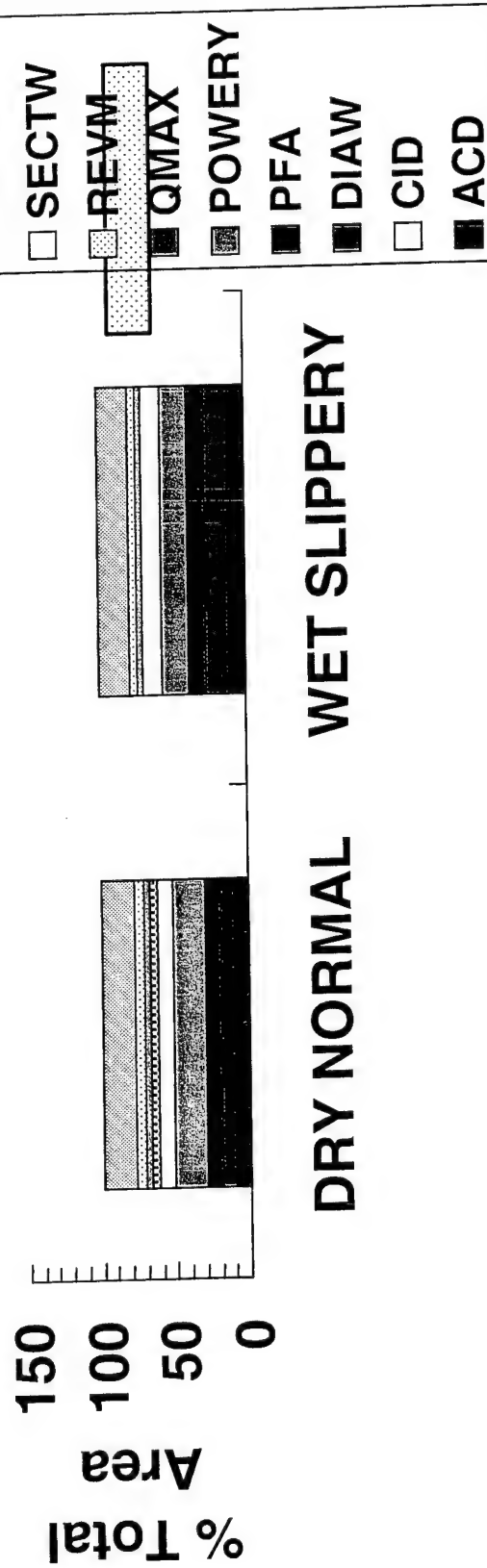
# Significant LVS Vehicle Parameters Mindanao, Philippines, Off- Road, 20% Variance

Waterways Experiment Station



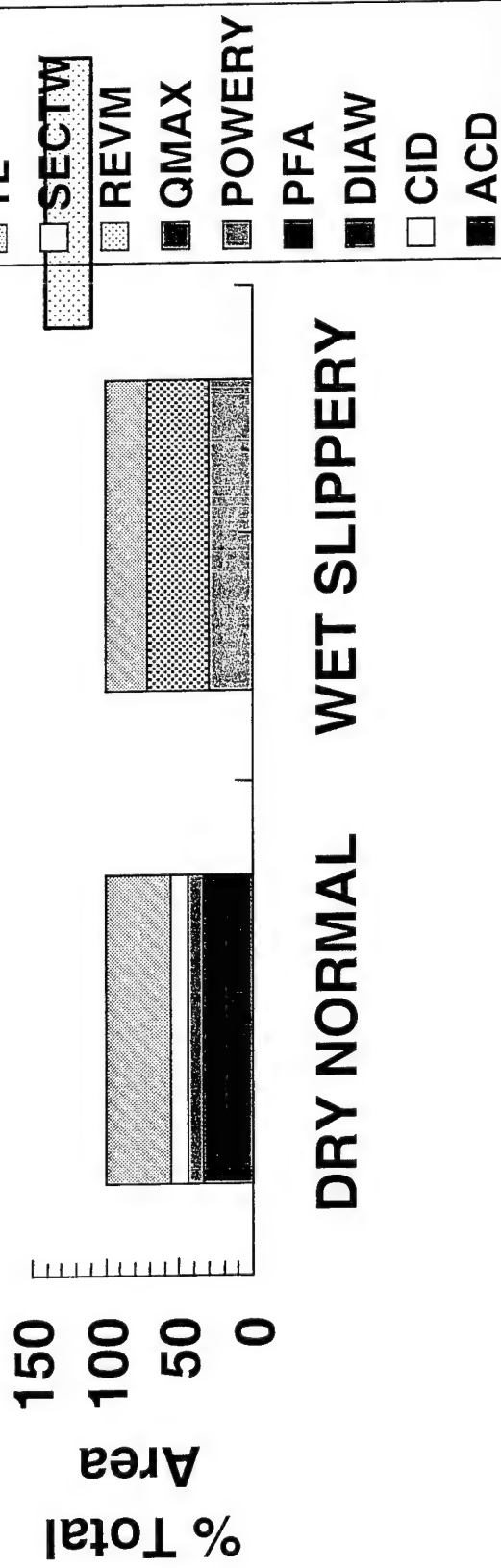
# Significant LVS Vehicle Parameters 3421i, South Korea, Off- Road, 20% Variance

Waterways Experiment Station



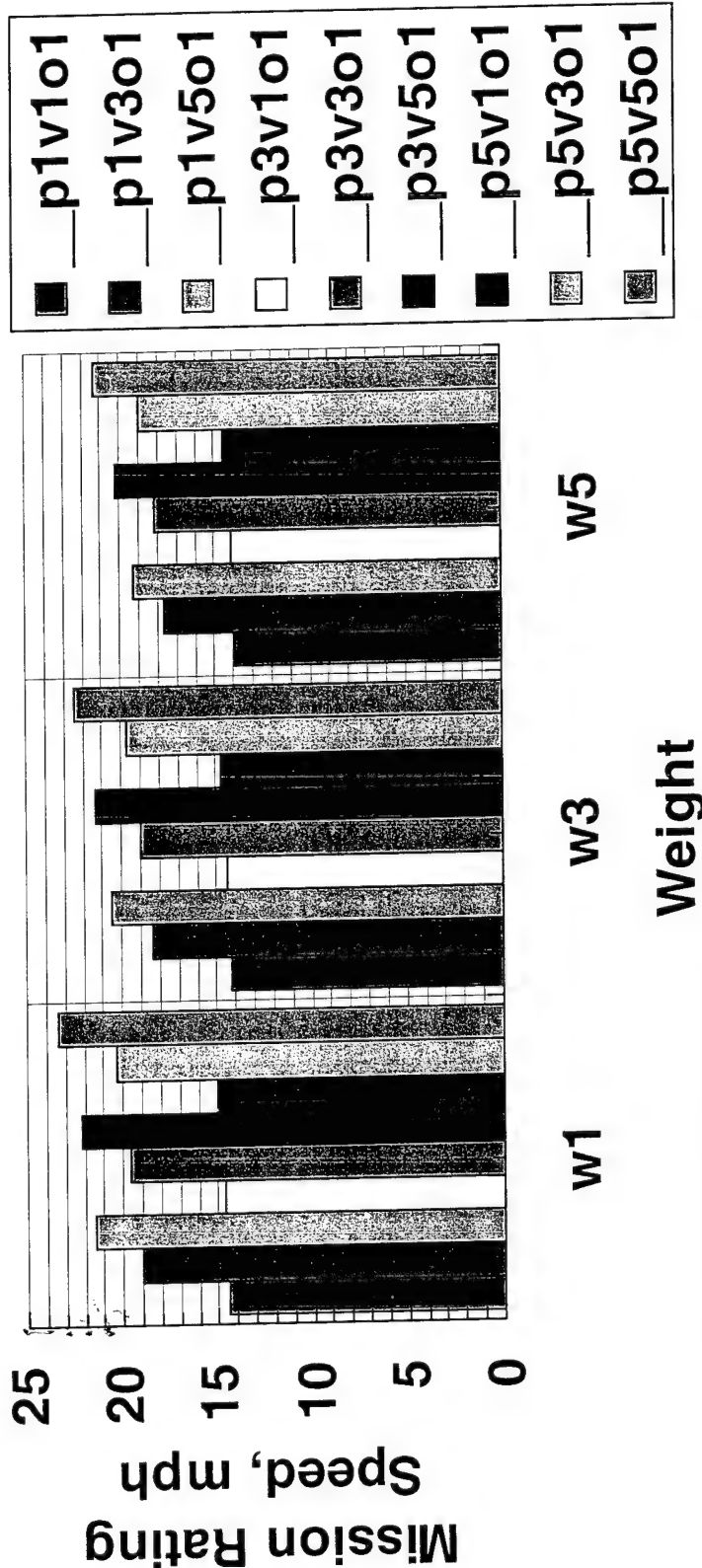
# Significant LVS Vehicle Parameters 5546i, Saudi Arabia/Kuwait, Off-Road, 20% Variance

Waterways Experiment Station



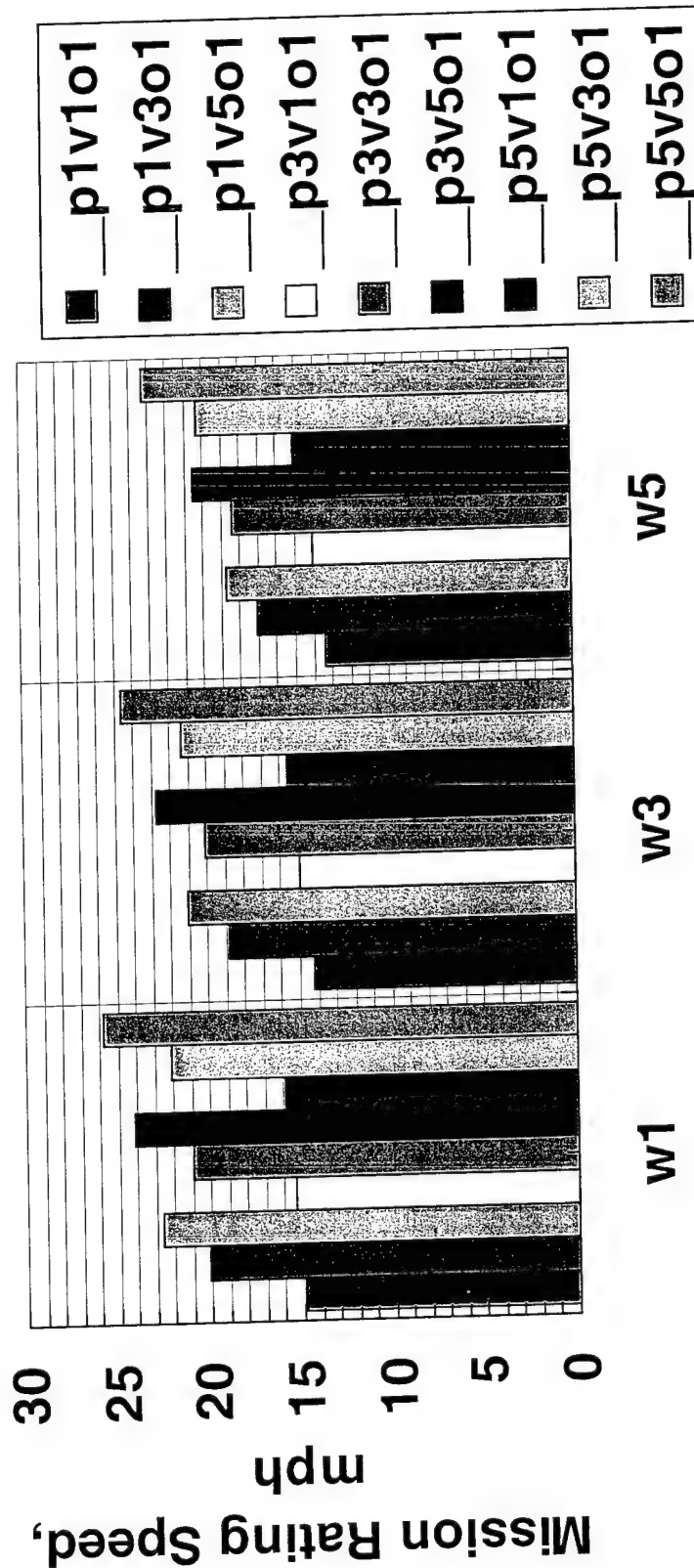


# LVSR MSR Performance in the Philippines



Payload Weight	Engine Power	Suspension (Ride)	Suspension (Shock)
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

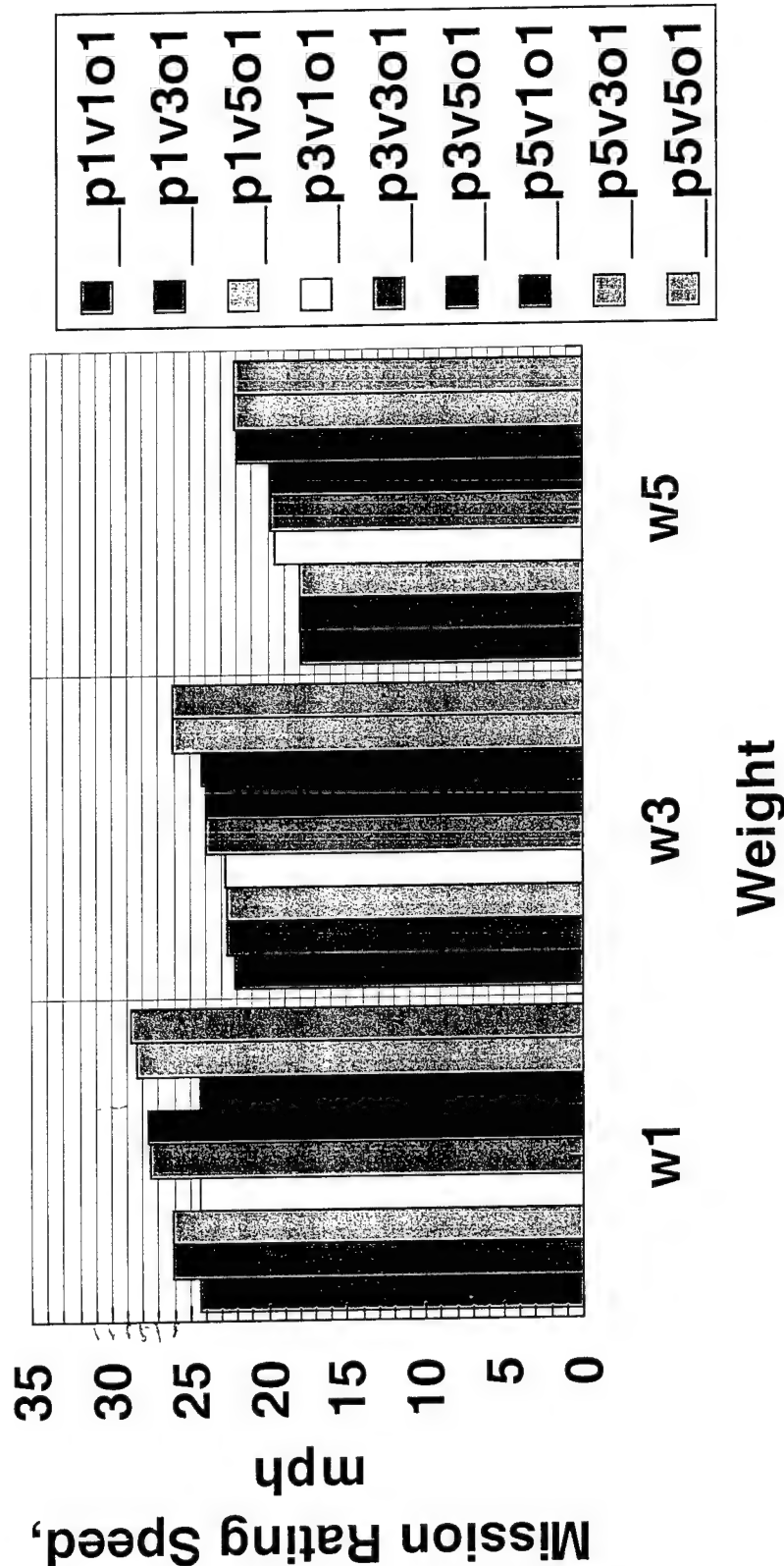
# LVSR MSR Performance in Korea



Waterways Experiment Station

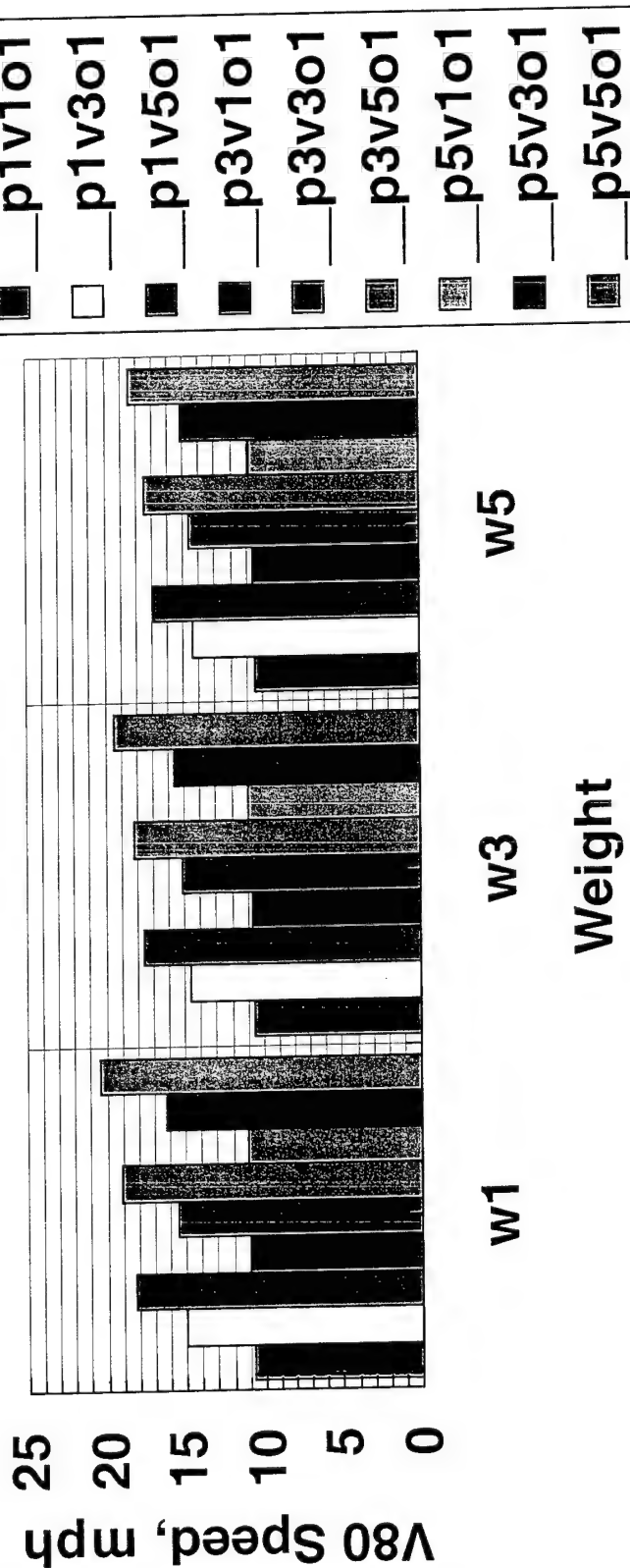
Payload Weight	Engine Power	Suspension (Ride)	Suspension (Shock)
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

# LVSR MSR Performance in Kuwait



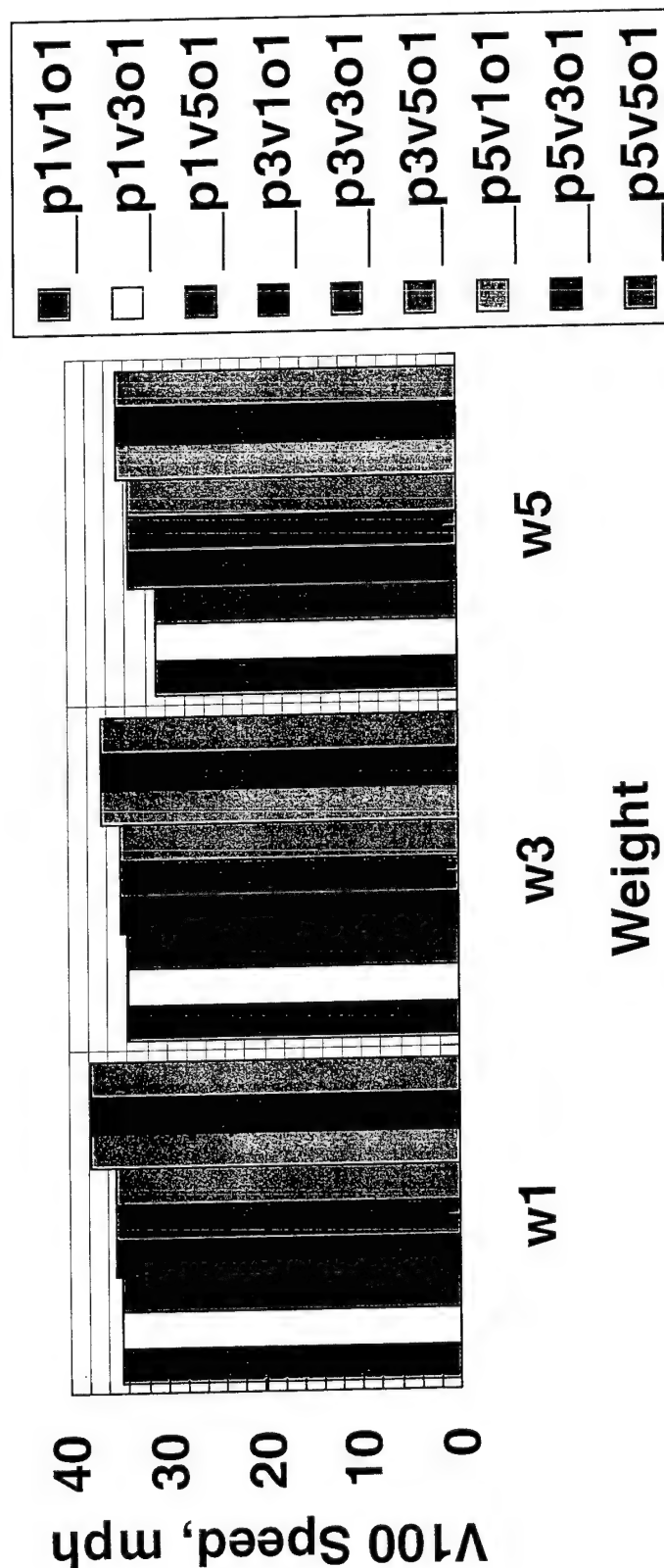
Payload Weight	Engine Power	Suspension (Ride)	Suspension (Shock)
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

# LVSR Speed Performance in the Philippines Off-Road



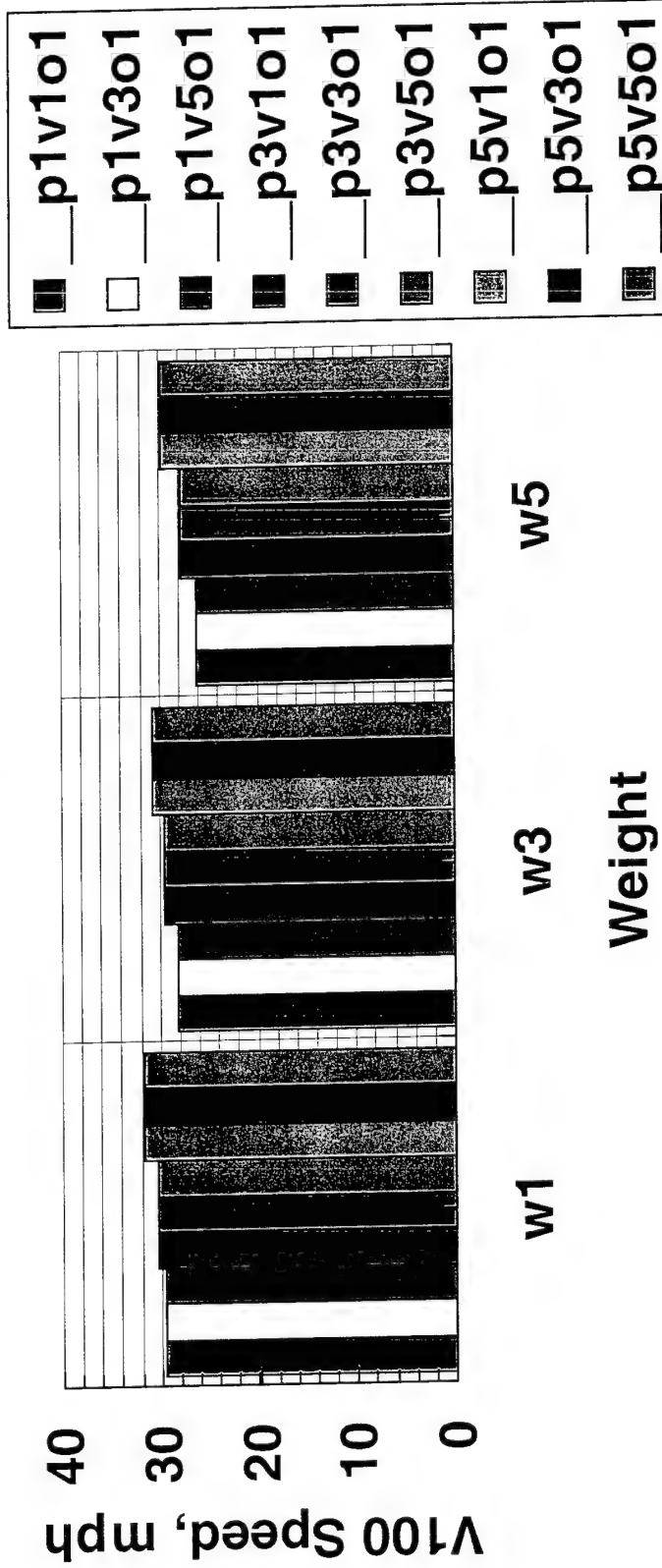
Payload Weight	Engine Power	Suspension (Ride)	Suspension (Shock)
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

# LVSR Speed Performance in the Philippines Primary Roads



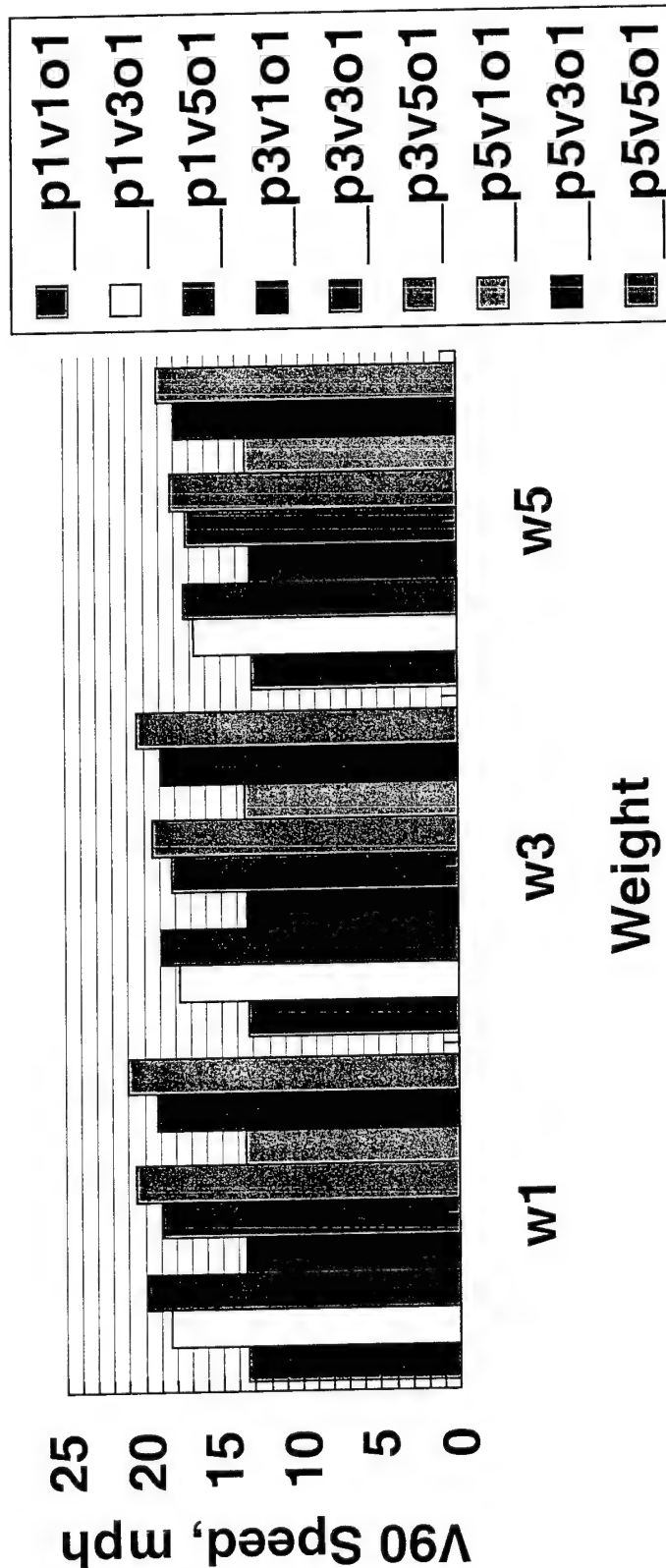
<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

# LVSR Speed Performance in the Philippines Secondary Roads



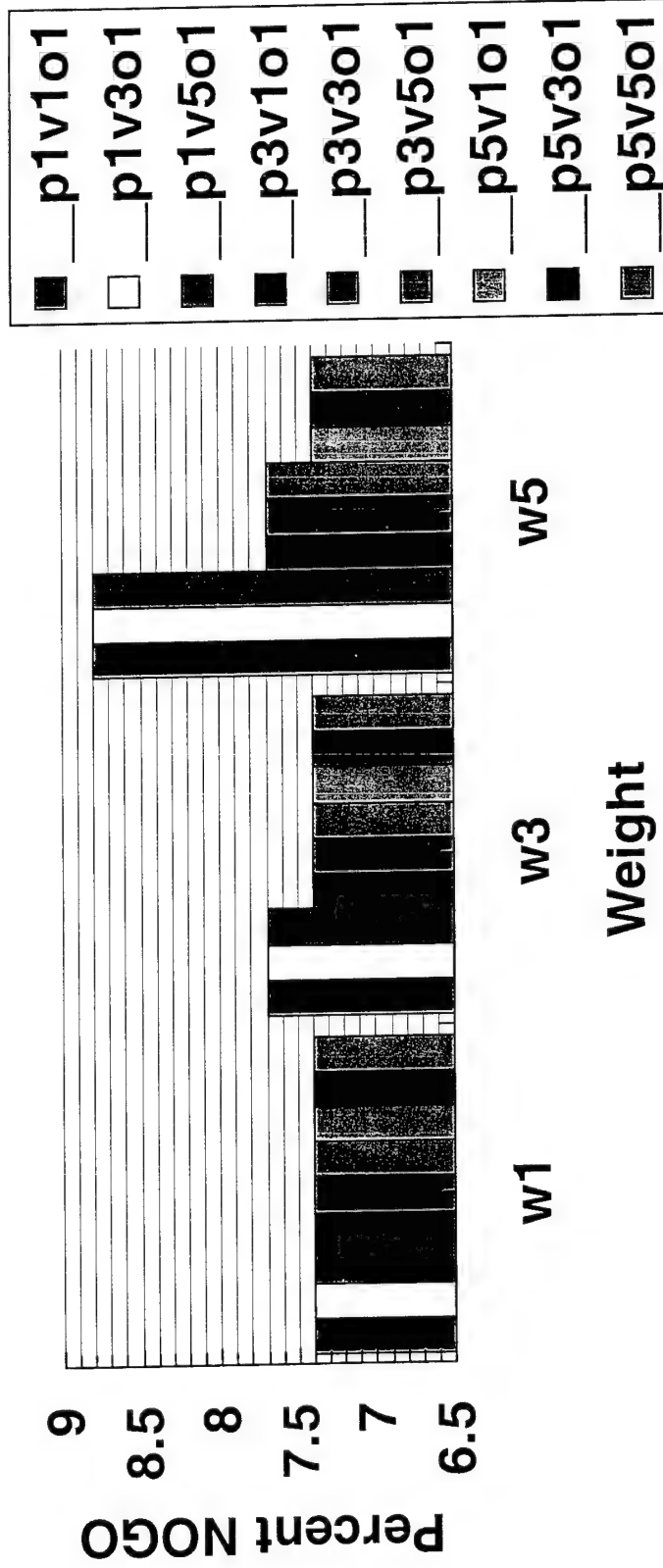
Payload Weight	Engine Power	Suspension (Ride)	Suspension (Shock)
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

# LVSR Speed Performance in the Philippines Trails



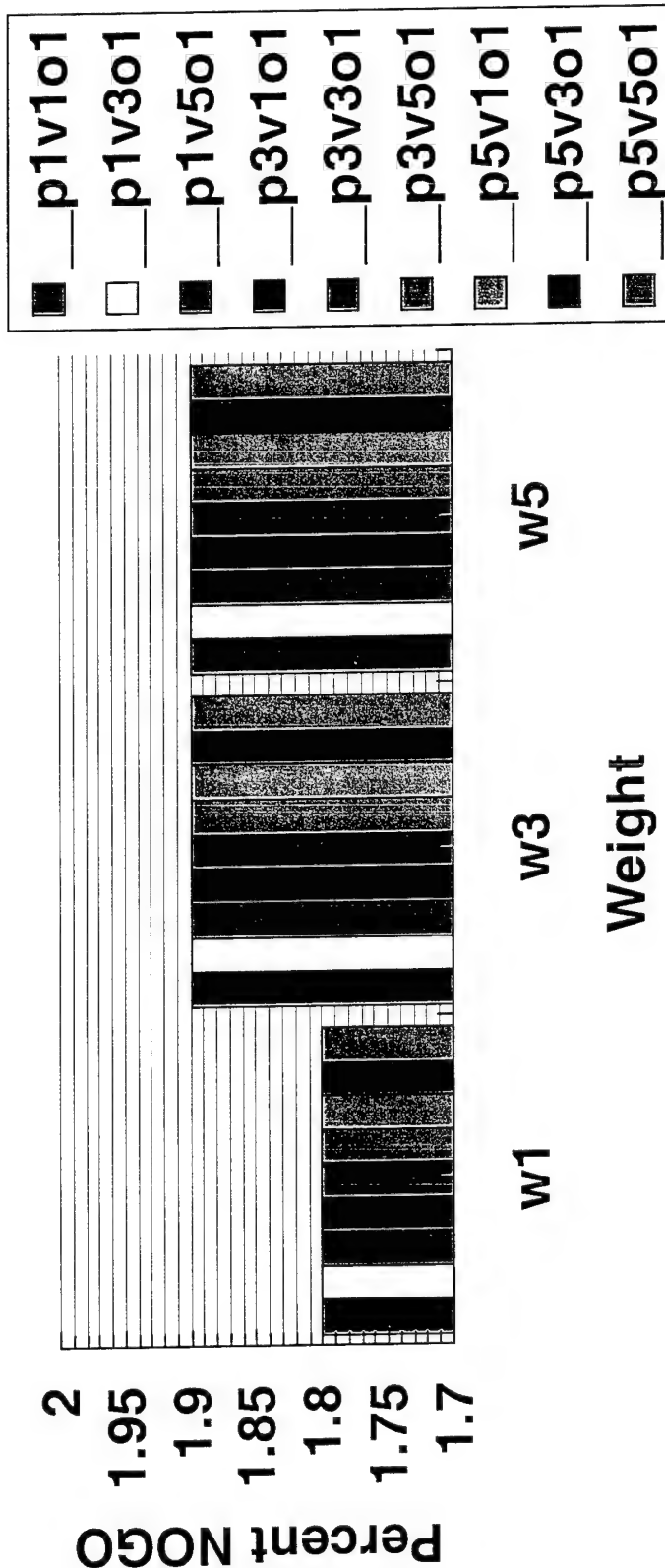
Payload Weight	Engine Power	Suspension (Ride)	Suspension (Shock)
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

# LVSR NOGO Performance in the Philippines Off-Road



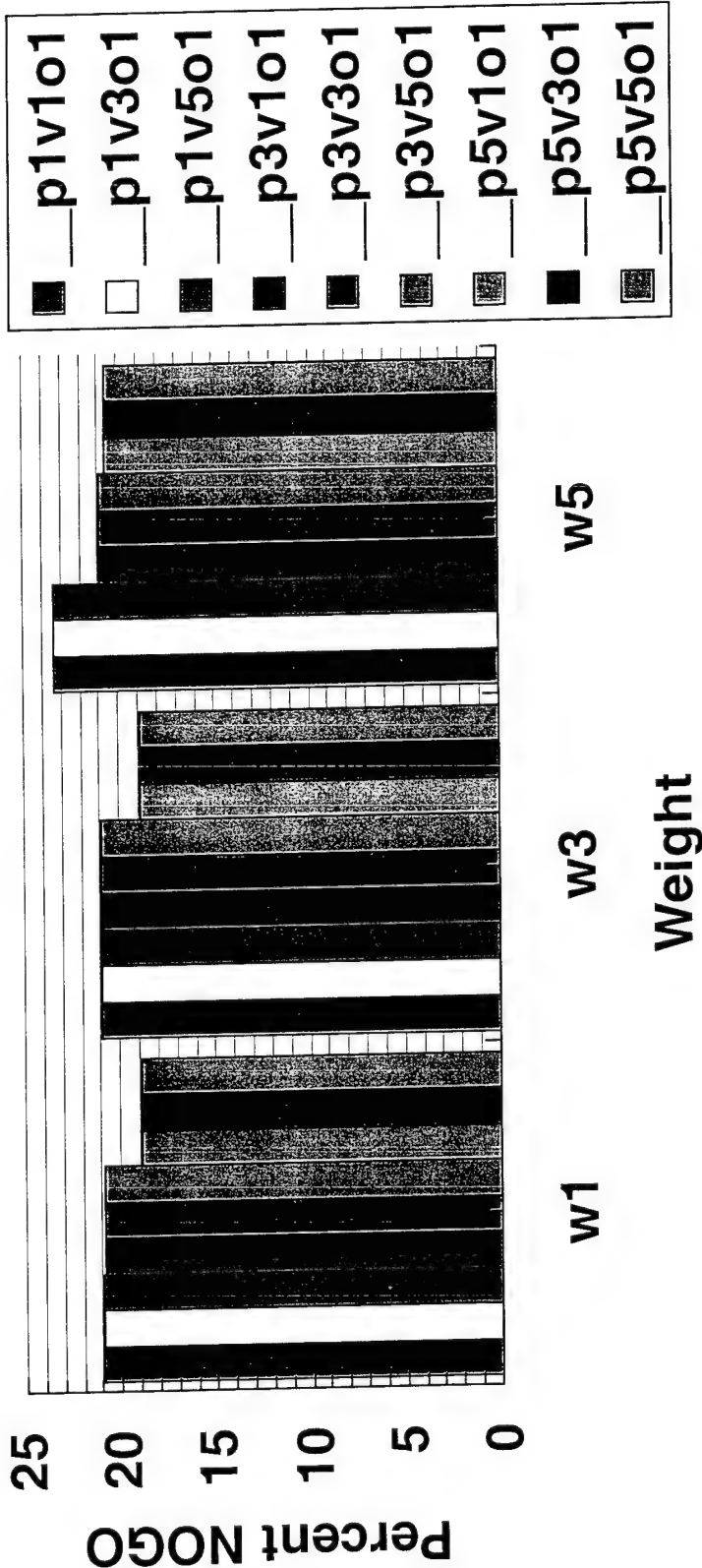
Payload Weight	Engine Power	Suspension (Ride)	Suspension (Shock)
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

# LVSR NOGO Performance in the Philippines On-Road



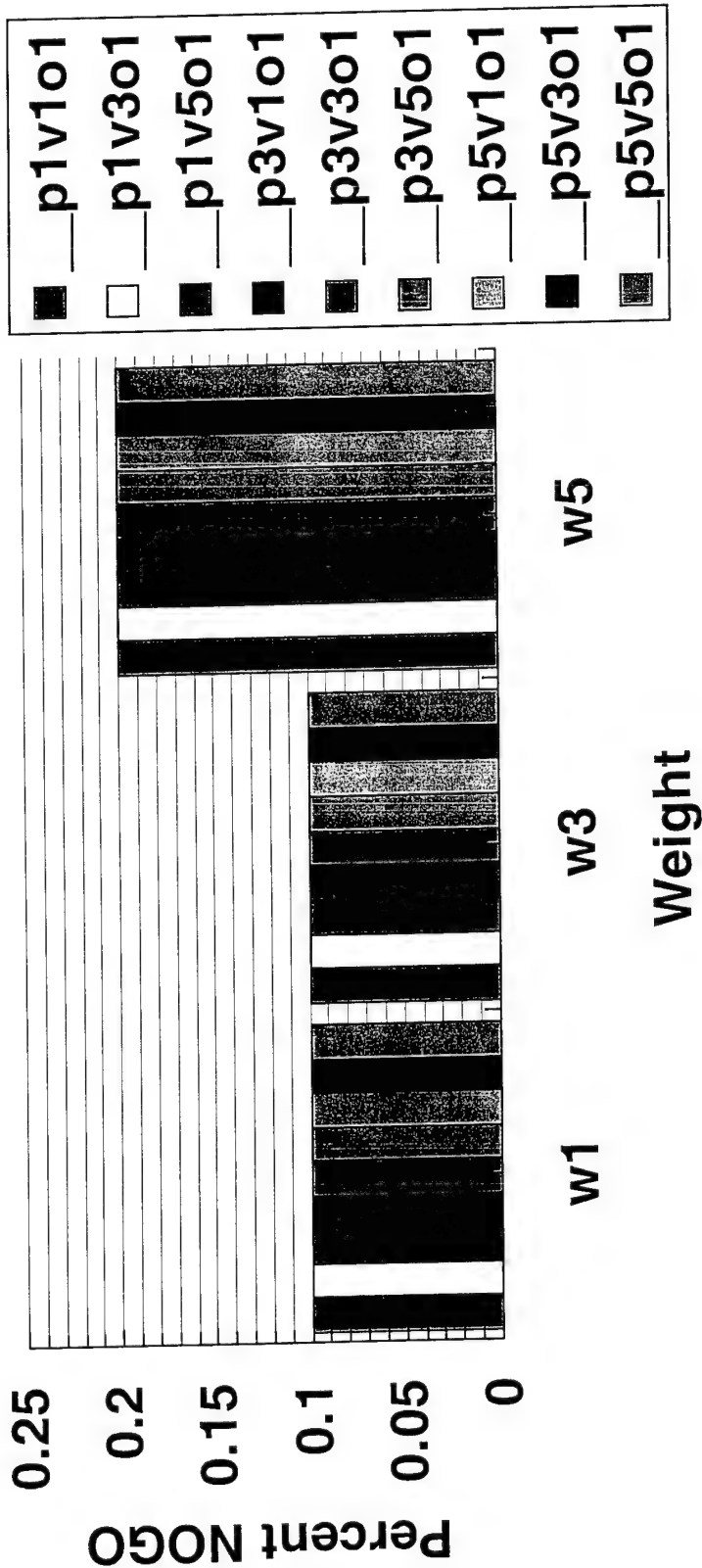
Payload Weight	Engine Power	Suspension (Ride)	Suspension (Shock)
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

# LVSR NOGO Performance in Korea Off-Road



<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

# LVSR NOGO Performance in Kuwait Off-Road

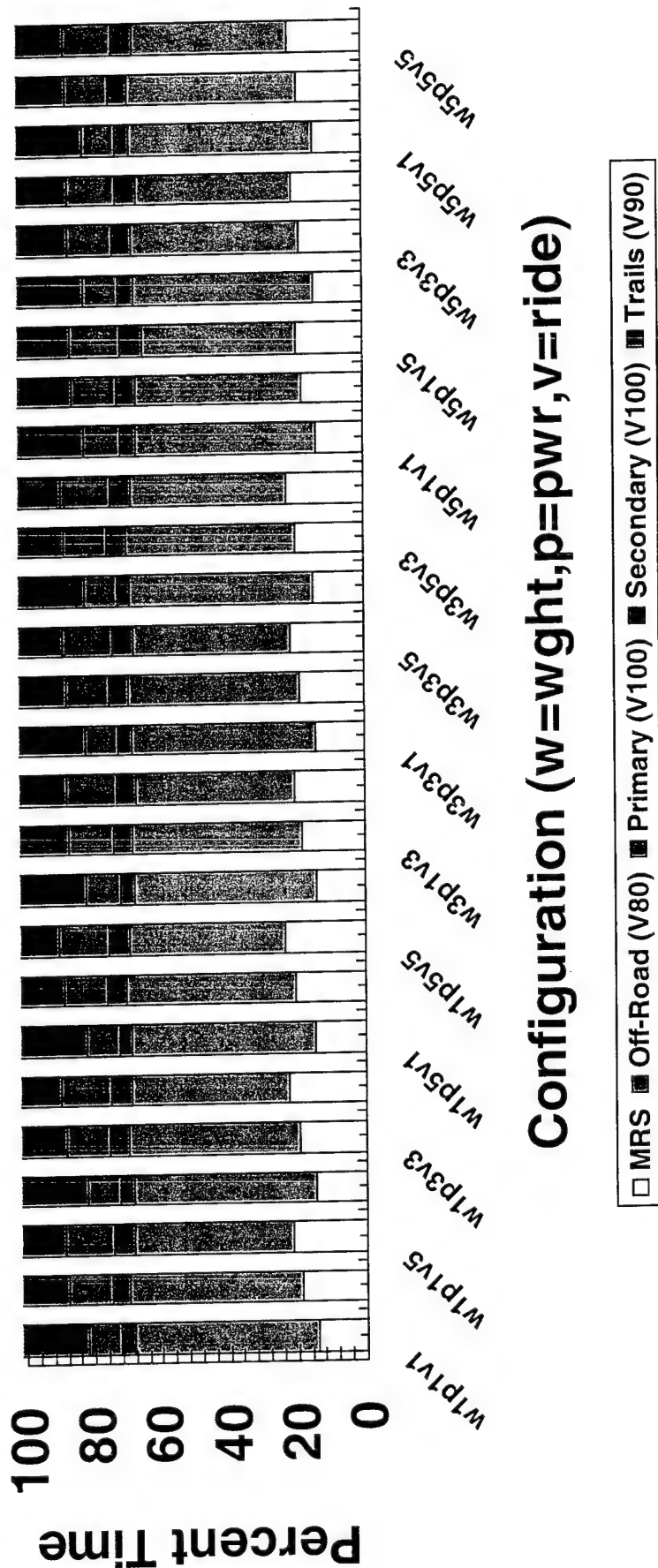


<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

Waterways Experiment Station

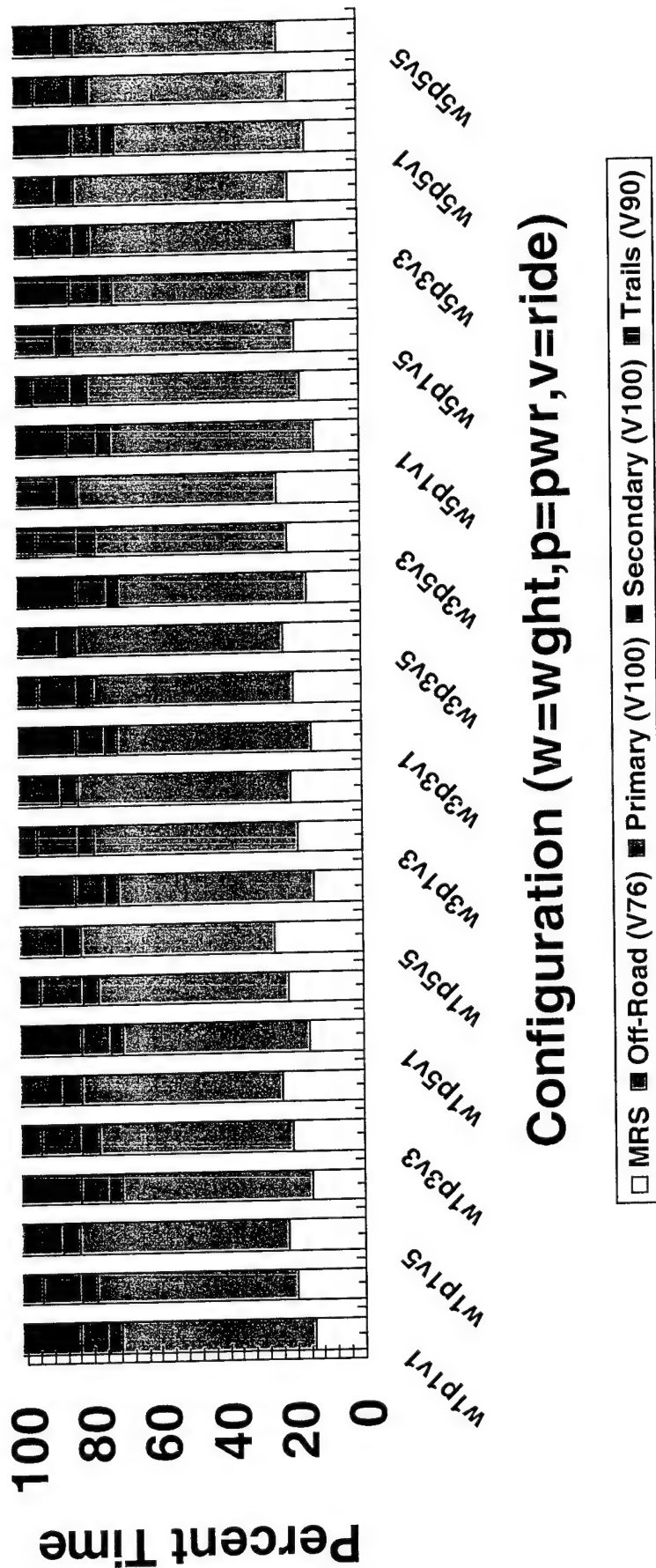
# LVSR Percent Times Off-Road and On-Road Philippines, Mindanao Dry Normal

Waterways Experiment Station



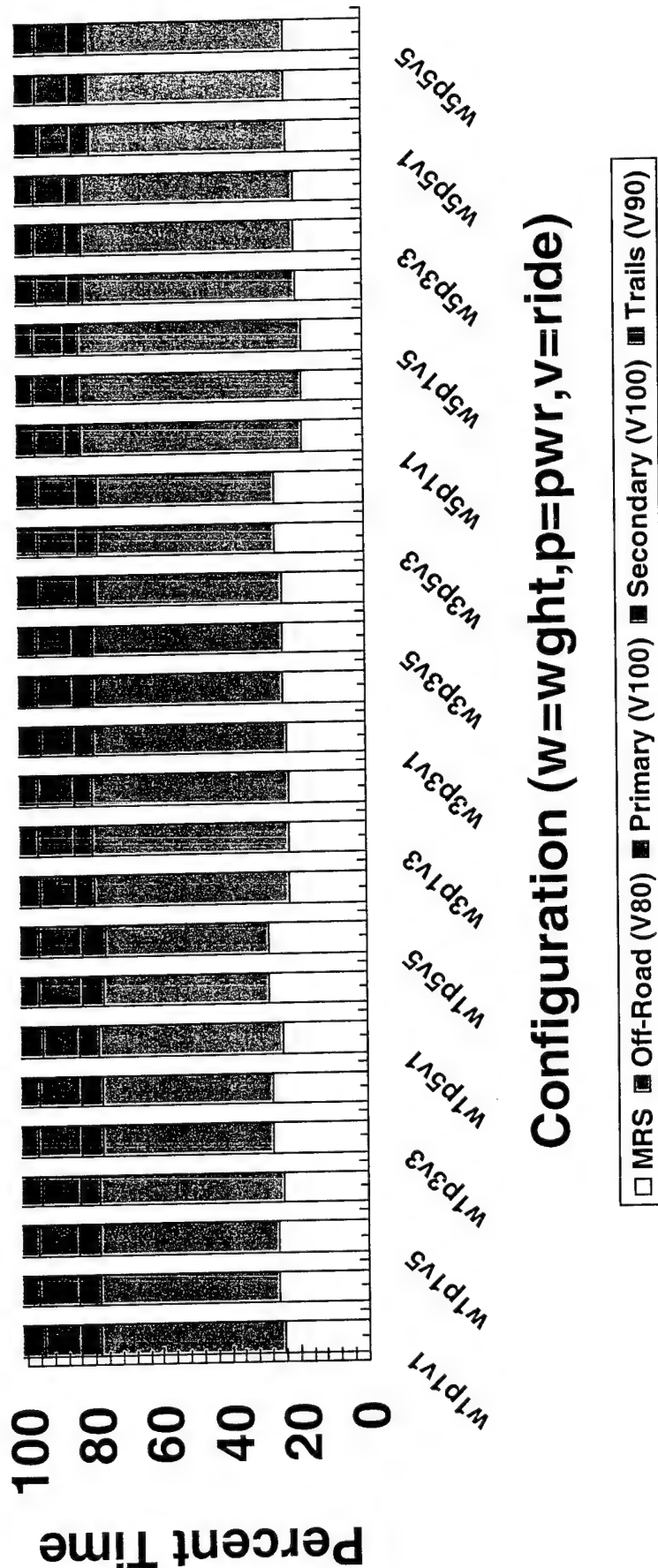
# LVSR Percent Times Off-Road and On-Road Korea, 3421i Dry Normal

Waterways Experiment Station



# LVSR Percent Times Off-Road and On-Road Kuwait, 5546i Dry Normal

Waterways Experiment Station



Response: MRS

Summary of Fit	
RSquare	0.978756
RSquare Adj	0.957774
Root Mean Square Error	0.838613
Mean of Response	20.07593
Observations (or Sum Wgts)	162

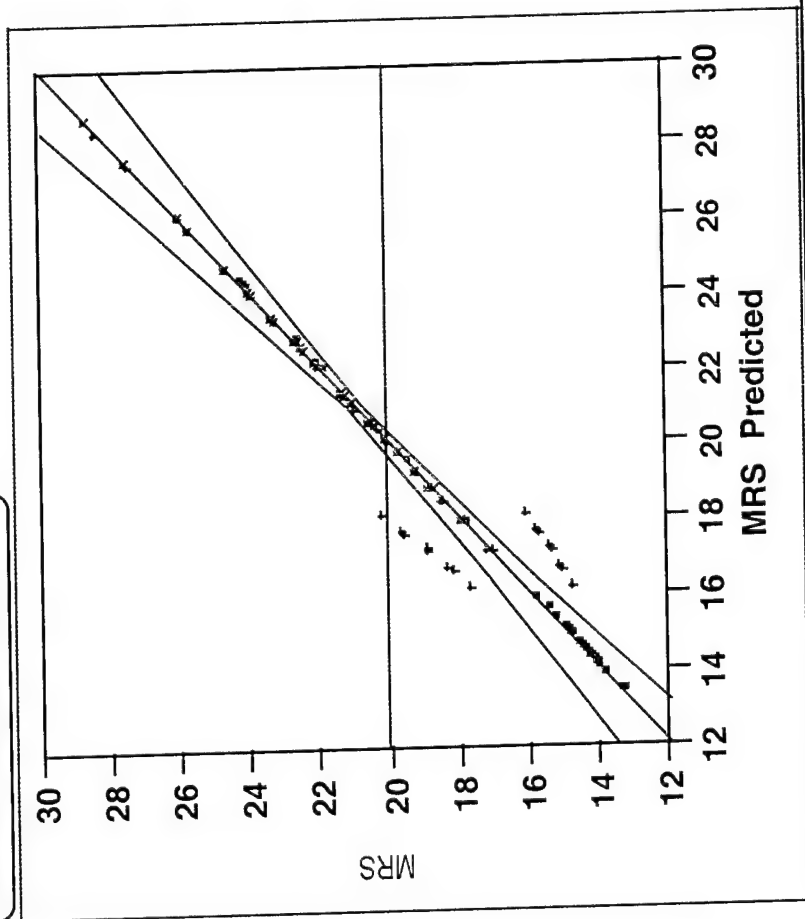
Parameter Estimates

Effect Test					
Source	Nparm	DF	Sum of Squares	F Ratio	Prob > F
Country	2	2	953.13000	677.6400	<.0001
Weight	2	2	296.84333	211.0446	<.0001
Country*Weight	4	4	141.73444	50.3840	<.0001
Power	2	2	132.25593	94.0291	<.0001
Country*Power	4	4	15.49407	5.5079	0.0006
Weight*Power	4	4	6.90296	2.4539	0.0523
Country*Weight*Power	8	8	5.08037	0.9030	0.5182
Ride	2	2	794.48481	564.8492	<.0001
Country*Ride	4	4	233.43407	82.9815	<.0001
Weight*Ride	4	4	22.88074	8.1337	<.0001
Country*Weight*Ride	8	8	4.69037	0.8337	0.5757
Power*Ride	4	4	13.82370	4.9141	0.0013
Country*Power*Ride	8	8	1.84519	0.3280	0.9530
Weight*Power*Ride	8	8	0.35963	0.0639	0.9998
Country*Weight*Power*Ride	16	16	1.55148	0.1379	1.0000

☐ = significant interaction between factors (Prob >F is < .05)
 ☐ = significant factor influencing mrs (Prob >F is < .05)

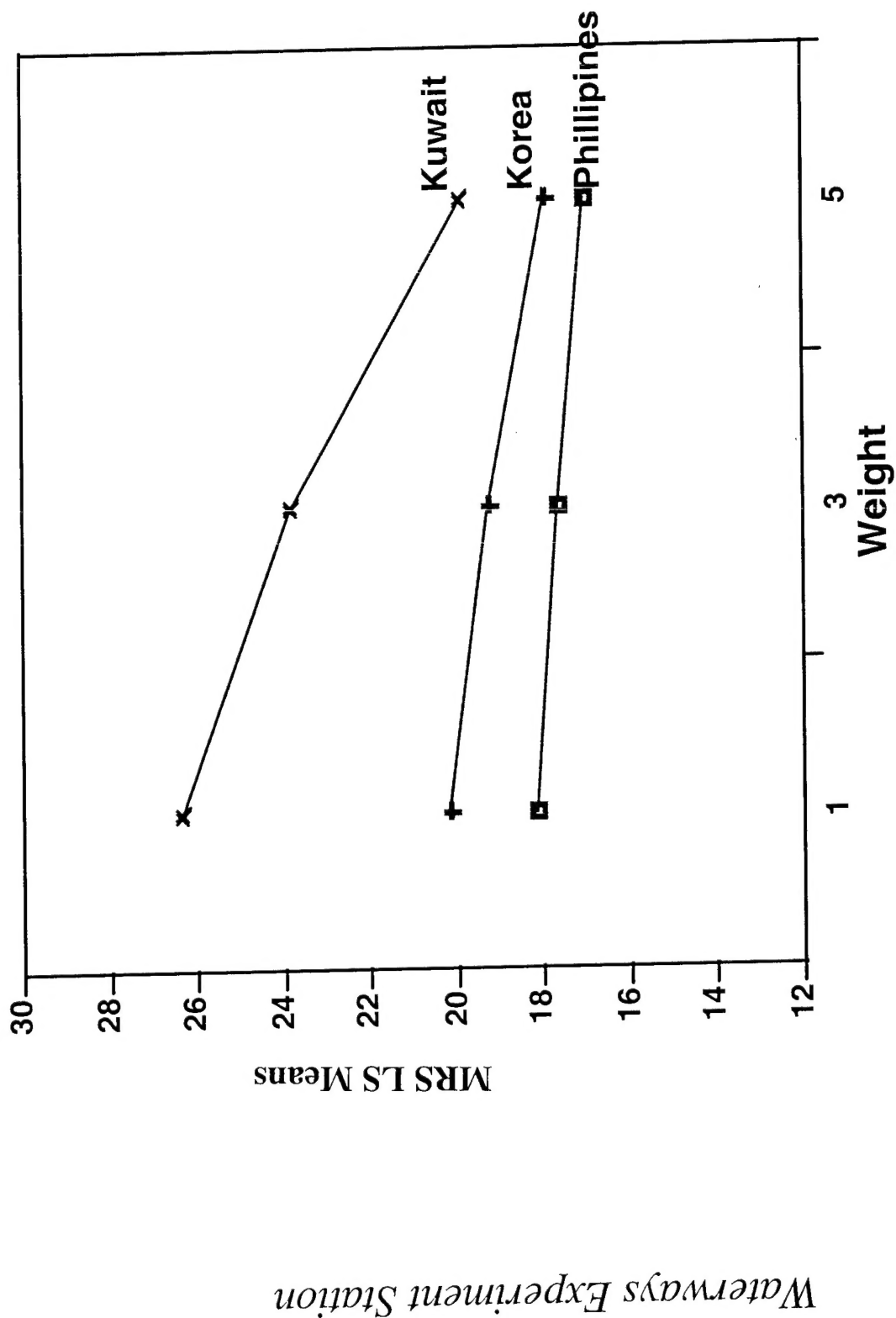
# Waterways Experiment Station

Whole-Model Test

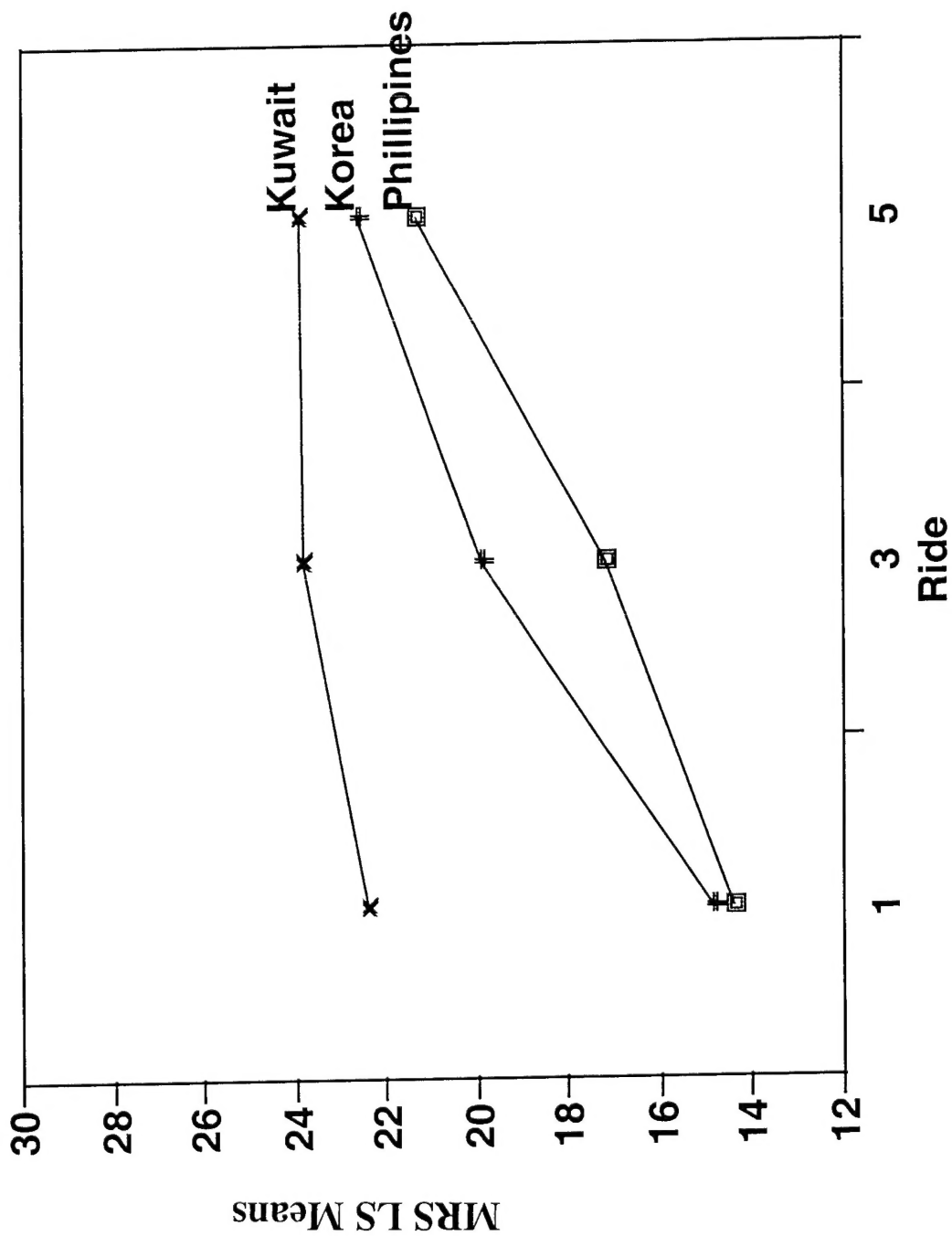


Analysis of Variance

Source	DF	Sum of Squares	Mean Square	F Ratio
Model	80	2624.5111	32.8064	46.6482
Error	81	56.9650	0.7033	Prob>F
C Total	161	2681.4761		<.0001



Waterways Experiment Station



Waterways Experiment Station

